ASSP For Power Management Applications (Mobile Phones)

Power Management IC for Mobile Phone

MB3893A

DESCRIPTION

MB3893A is a multi-function power management IC chip with built-in 4-channel series regulator providing the output control functions and power supply drop detection circuits required for mobile phones. The MB3893A includes lithium-ion battery charge control functions and functions as a built-in power management system ideal for mobile phone devices.

FEATURES

[Power Supply Control Unit]

- Supply voltage range
- Low power consumption current during standby
- Built-in 4-channel low-saturation voltage type series regulator

: 2.5 V/2 channels, 1.8 V/1 channels,

- 2.0 V/1 channels (1.9 V and 2.2 V available as mask options)
- Built-in interruption detection and supply recovery functions eliminate need for supplementary power supply
- · Built-in On/Off switch circuit with accidental operation prevention function
- Accurate supply voltage drop detection
- Built-in power-on reset (OUT1) function
- Detection voltage with hysteresis

[Charge Control Unit]

- Supply voltage range
- : VIN = 3.4 V to 5.9 V
- Built-in lithium-ion battery charge control functions
- Charging voltage

: 4.1 V/4.2 V (switchable)

- Built-in preliminary charging function
- Built-in re-charging function
- Built-in timer functions
- · Built-in battery temperature detection function





: Vcc = 3.1 V to 4.8 V : 110 µA (Max.)

PIN ASSIGNMENT



■ PIN DESCRIPTION

Pin No.	Symbol	I/O	Description
1	VIN	—	Power supply terminal for the charge control unit.
2	CONT	0	External P-ch MOS FET output control terminal.
3	ISENSE+	I	Charge current detection input terminal.
4	ISENSE-	I	Charge current/voltage detection input terminal.
5	DRST	I	Power supply drop detection reset input terminal. 100 k Ω pull-down.
6	CONT5	I	Battery voltage measurement setting terminal. 100 k Ω pull-down.
7	C1	I	POR delay time setting capacitor connection terminal.
8	GND1	—	Ground terminal.
9	ONOFF1	I	REG ON control terminal. 100 k Ω pull-up: VCC (edge input)
10	VREF1M	0	Reference voltage output terminal. (Power supply control unit)
11	XON	I	REG On control terminal. 100 k Ω pull-up: VCC (with delay)
12	CR1	I	Power supply drop detection judgement capacitor-resistor connection terminal.
13	CR2	I	Cutoff detection judgement capacitor-resistor connection terminal.
14	CONT1	I	REG ON control terminal. 100 kΩ pull-up: VCC
15	RC1	I	XON delay time setting capacitor-resistor connection terminal. 470 k Ω pull-up: VCC (XON = L _o)
16	VCONT	0	REG rise signal output terminal.
17	ONOFF2	I	REG ON control terminal. 100 k Ω pull-up: VCC (edge input)
18	POFF	I	REG OFF control terminal. 100 k Ω pull-down (OFF)
19	VFIL	0	REG reference terminal.
20	TEST		Testing auxiliary terminal. (normally GND connection)
21	VCC2		REG4 power supply terminal.
22	OUT4	0	REG4 output terminal. (2.5 V Typ.)
23	SW1	0	Battery voltage measurement output terminal.
24	LEDEN	I	LED input terminal. 100 k Ω pull-down (LEDR : "L" = ON, "H" = OFF)
25	LED	I	LED input terminal. 100 k Ω pull-down (LEDG : "H" = ON, "L" = OFF)
26	CONT2	I	REG3 On/Off control terminal. 470 kΩ pull-up : OUT1
27	OUT3	0	REG3 output terminal. (2.0 V Typ.)
28	VCC1	—	REG1, 2, 3 supply terminal.
29	OUT1	0	REG1 output terminal. (2.5 V Typ.)
30	OUT2	0	REG2 output terminal. (1.8 V Typ.)
31	FULL	0	Charge state detection signal output terminal. (full charge)
32	CHARGE	0	Charge state detection signal output terminal. (charging)
33	VBDET2	0	Power supply drop detection output signal terminal.

Pin No.	Symbol	I/O	Description
34	VBDET1	0	Power supply drop detection output signal terminal. (10 s Typ.)
35	XRST	0	POR reset output terminal.
36	ICONT	I	REG output mode switching terminal. 100 k Ω pull-down
37	LEDG	0	LED output terminal. (open drain)
38	LEDR	0	LED output terminal. (open drain)
39	GND2		Ground terminal.
40	VCC		Power supply terminal for the power supply control unit
41	INTV	_	Internal power supply terminal.
42	CVC	I	Phase compensation capacitor connection terminal.
43	BATSENSE	I	Battery connection verification input terminal. 100 k Ω pull-up : VIN
44	COSC	I	Oscillator frequency setting capacitor connection terminal. 100 pF + 19 pF (reference capacitance)
45	ROSC	I	Oscillator frequency setting resistance connection terminal.
46	BATSEL	I	Charge setting voltage switching terminal. 100 k Ω pull-up : VIN (OPEN = 4.1 V, "L" = 4.2 V)
47	VREFTH	0	Temperature detection reference voltage terminal
48	TSENSE	I	Temperature detection input terminal.

BLOCK DIAGRAM



Charge control unit



ABSOLUTE MAXIMUM RATINGS

Paramotor	Symbol	Condition	Rat	Unit	
Faidilielei	Symbol	Condition	Min.	Max.	Unit
Power supply voltage	Vcc	21, 28, 40 pin	-0.3	7	V
rower supply vollage	Vin	1 pin	-0.3	15	V
	VIN1	2, 37, 38, 42 to 48 pin	-0.3	VIN + 0.3	V
Input voltage	V _{IN2}	3 to 7, 9 to 20, 22 to 27, 29 to 36, 41 pin	-0.3	Vcc + 0.3	V
Power dissination	Pa	Ta≤+25 °C (LQFP-48P)	_	860*	mW
	PD	Ta≤+25 °C (TQFP-48P)	_	1230*	mW
Storage temperature	Tstg	_	-55	+125	°C

* : The packages are mounted on the dual-sided epoxy board (10 cm \times 10 cm).

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

■ RECOMMENDED OPERATING CONDITIONS

Baramotor	Symbol	Condition		Unit			
Falailletei	Symbol	Condition	Min.	Тур.	Max.	Sint	
Power supply voltage	Vcc	_	3.1		4.8	V	
	Vin		3.4	5.3	5.9	V	
REG capacitor guarantee value	Co	OUT1 to OUT4 terminal	0.8	1.0	—	μF	
REG capacitor ESR guarantee value	Resr	_	0.02		0.6	Ω	
VREF1M capacitor guarantee value	Co	VREF1M terminal		_	100	pF	
Operating ambient temperature	Та	_	-30	+25	+85	°C	

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

■ ELECTRICAL CHARACTERISTICS

(Ta = -30 to +85 °C, VCC = 3.1 V to 4.8 V)

	Paramotor		Din No	Conditions	Value			Unit
	Falailletei	Symbol	FIII NO.	Conditions	Min.	Тур.	Max.	Unit
Reference voltage block	Reference voltage	Vfil	19	VFIL = 0 mA	1.19	1.23	1.27	V
		V _{01s}	29	OUT1 = 0 to -500 μA, ICONT = "L" level	2.41	2.50	2.59	V
	Oulput voltage	V _{01F}	29	OUT1 = 0 to -70 mA, ICONT = "H" level	2.41	2.50	2.59	V
	Input stability	Line	29	OUT1 = 0 to -70 mA, ICONT = "H" level	_		20	mV
	Load stability	Load	29	OUT1 = 0 to -70 mA, ICONT = "H" level	-30		0	mV
ck [REG1]	Ripple rejection	R.R	29 -	VIN = 0.2 Vrms, f = 1 kHz, OUT1 = 0 to -70 mA, ICONT = "H" level	50			dB
e control blc				VIN = 0.2 Vrms, f = 10 kHz, OUT1 = 0 to -70 mA, ICONT = "H" level	50			dB
ıstant voltag	Noise	VNOVL1	29	f = 10 Hz to 20 kHz, VCC = 3.6 V, OUT1 = -70 mA, ICONT = "H" level			95	μVrms
Cor	Overcurrent protection value	IL1	29	OUT1 = 90 %, ICONT = "H" level	100	200	400	mA
	Rise time	t _{R1}	29	Pin 9, 14, 17 controlOUT1 = 1.0 μF,OUT1 = 36 Ω,OUT1 = 90 %			200	μs
		t _{R2}	29	VCC control OUT1 = 1.0 μ F, OUT1 = 36 Ω , OUT1 = 90 %			150	ms

Paramotor		Sumhel	Pin No	Conditions	Value			Unit
	rarameter	Symbol	FIII NO.	Conditions	Min.	Тур.	Max.	Unit
	Output voltogo	Vo2s	30	OUT2 = 0 to $-500 \ \mu$ A, ICONT = "L" level	1.71	1.80	1.89	V
	Oulput voltage	Vo2f	30	OUT2 = 0 to -50 mA, ICONT = "H" level	1.71	1.80	1.89	V
	Input stability	Line	30	OUT2 = 0 to -50 mA, ICONT = "H" level			20	mV
stant voltage control block [REG2]	Load stability	Load	30	OUT2 = 0 to -50 mA, ICONT = "H" level	-30		0	mV
	Ripple rejection	R.R	30	VIN = 0.2 Vrms, f = 1 kHz, OUT2 = 0 to –50 mA, ICONT = "H" level	50			dB
				VIN = 0.2 Vrms, f = 10 kHz, OUT2 = 0 to -50 mA, ICONT = "H" level	50			dB
	Noise	VNOVL2	30	f = 10 Hz to 20 kHz, VCC = 3.6 V, OUT2 = -50 mA, ICONT = "H" level			95	μVrms
Cor	Overcurrent protection value	IL2	30	OUT2 = 90 %, ICONT = "H" level	65	130	260	mA
	Rise time	t _{R1}	30	Pin 9, 14, 17 control OUT2 = $1.0 \ \mu$ F, OUT2 = $36 \ \Omega$, OUT2 = $90 \ \%$			200	μs
	Rise time	t _{R2}	30	VCC control OUT2 = 1.0μ F, OUT2 = 36Ω , OUT2 = 90%			150	ms

(Ta = -30 to +85 °C, VCC = 3.1 V to 4.8 V)

(Ta = -30 to +85 °C, VCC = 3.1 V to 4.8 V)

	Paramotor	Symbol	Pin No.	Conditions		Unit		
	Farameter	Symbol		Conditions	Min.	Тур.	Max.	Unit
		Voss	27	OUT3 = 0 to -500 μA, ICONT = "L" level, CONT2 = "L" level	(1.81) 1.91 (2.11)	(1.90) 2.00 (2.20)	(1.99) 2.09 (2.29)	V
	Output voltage	Vojf	27	OUT3 = 0 to -70 mA, ICONT = "H" level, CONT2 = "L" level	(1.81) 1.91 (2.11)	(1.90) 2.00 (2.20)	(1.99) 2.09 (2.29)	V
	Input stability	Line	27	OUT3 = 0 to -70 mA, ICONT = "H" level, CONT2 = "L" level	_	_	20	mV
	Load stability	Load	27	OUT3 = 0 to -70 mA, ICONT = "H" level, CONT2 = "L" level	-30	_	0	mV
ck [REG3]	Ripple rejection	R.R	27	VIN = 0.2 Vrms, f = 1 kHz, OUT3 = 0 to -70 mA, ICONT = "H" level, CONT2 = "L" level	50	_		dB
tage control blo				VIN = 0.2 Vrms, f = 10 kHz, OUT3 = 0 to -70 mA, ICONT = "H" level, CONT2 = "L" level	50	_		dB
Constant vol	Noise	Vnovl3	27	f = 10 Hz to 20 kHz, VCC = 3.6 V, OUT3 = -70 mA, ICONT = "H" level, CONT2 = "L" level,		_	95	μVrms
	Overcurrent protection value	lı2	27	OUT3 = 90 %, ICONT = "H" level, CONT2 = "L" level	65	170	340	mA
	Rise time	tr1	27	Pin 9, 14, 17 control OUT3 = 1.0 μ F, OUT3 = 27 Ω , OUT3 = 90 %, CONT2 = "L" level		_	200	μs
		t _{R2}	27	VCC control OUT3 = 1.0 μ F, OUT3 = 27 Ω , OUT3 = 90 %, CONT2 = "L" level		_	150	ms

(Ta = -30	0 to +85 °C	, VCC = 3.1	V to 4.8 V)
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	Parameter		Pin No	Conditions		Value		Unit
	i arameter	Symbol		conditions	Min.	Тур.	Max.	Unit
		V _{04s}	22	OUT4 = 0 to $-500 \ \mu$ A, ICONT = "L" level	2.41	2.50	2.59	V
	Output voltage	V04F	22	OUT4 = 0 to -60 mA, ICONT = "H" level	2.41	2.50	2.59	V
	Input stability	Line	22	OUT4 = 0 to -60 mA, ICONT = "H" level			20	mV
4	Load stability	Load	22	OUT4 = 0 to -60 mA, ICONT = "H" level	-30		0	mV
ock [REG	Pipple rejection	DD	22	VIN = 0.2 Vrms, f = 1 kHz, OUT4 = 0 to -60 mA, ICONT = "H" level	50			dB
nt voltage control blo	Ripple rejection	K.K	22	VIN = 0.2 Vrms, f = 10 kHz, OUT4 = 0 to -60 mA, ICONT = "H" level	50	_		dB
	Noise	Vnovl4	22	f = 10 Hz to 20 kHz, VCC = 3.6 V, OUT4 = -60 mA, ICONT = "H" level			95	μVrms
Const	Overvoltage protection value	IL4	22	OUT4 = 90 %, ICONT = "H" level	80	160	320	mA
	Pico timo	t _{R1}	22	Pin 9, 14, 17 control OUT4 = $1.0 \ \mu$ F, OUT4 = $42 \ \Omega$, OUT4 = $90 \ \%$			200	μs
		t _{R2}	22	VCC control OUT4 = 1.0 μ F, OUT4 = 42 Ω , OUT4 = 90 %			150	ms
	Output voltage	Vo	10	VREF1M = 0 mA, CONT5 = "H" level	1.19	1.23	1.27	V
	Output current	lo	10	CONT5 = "H" level	-1	—		mA
REF1M	Invalid current	ICCVR	40	VREF1M = -1 mA, VCC = 3.6 V, CONT5 = "H" level		0.3	1.4	mA
>	Input stability	Line	10	VREF1M = 0 to -1 mA, CONT5 = "H" level			20	mV
	Load stability	Load	10	VREF1M = 0 to -1 mA, CONT5 = "H" level	-30		0	mV

(Ta = -30 to +85 °C, VCC = 3.1 V to 4.8 V)

	Parameter		Pin No	Conditions		Value			
	rarameter	Symbol	1 11 10.	Conditions	Min.	Тур.	Max.	Unit	
	Pipple rejection	DD	10	VIN = 0.2 Vrms, f = 1 kHz, VREF1M = 0 to -1 mA, CONT5 = "H" level	50	_		dB	
M ¹		K.K	10	VIN = 0.2 Vrms, f = 1 kHz, VREF1M = 0 to -1 mA, CONT5 = "H" level	44	49		dB	
VREF	Noise	Vnovl	10	f = 10 Hz to 20 kHz, VCC = 3.6 V, VREF1M = 0 to -1 mA, CONT5 = "H" level			95	μVrms	
	Rise time	tĸ	10	VREF1M = 1.2 kΩ, VREF1M = 90 %, CONT5 = "H" level		10	30	μs	
	Input voltage	Vı∟	5, 6, 18, 24, 25, 26		0.0		0.3	V	
		Vін	5, 6, 18, 24, 25, 26		$0.7 \times OUT1$		OUT1	V	
		Vı∟	9, 11, 14, 17		0.0		0.3 imes Vcc	V	
		Vін	9, 11, 14, 17	_	$0.7 imes V_{CC}$		Vcc	V	
		VIL	36	Ta = -20 °C to +75 °C	0.0		0.3	V	
		Vін	36	Ta = -20 °C to +75 °C	1.62		OUT1	V	
ock	VCONT terminal	Vol	16	VCONT = 1 mA	0.0		0.4	V	
O BI	output voltage	Vон	16	VCONT = -1 mA	2.0		Vcc	V	
ontro	XRST terminal	Vol	35	XRST = 20 μA	0.0		0.2	V	
Ц	output voltage	Vон	35	XRST = -100 μA	OUT1 - 0.2		OUT1	V	
/OF	VBDET1 terminal	Vol	34	$VBDET1 = 20 \ \mu A$	0.0		0.2	V	
NO	output voltage	Vон	34	VBDET1 = $-20 \ \mu A$	OUT1 - 0.2		OUT1	V	
	VBDET2 terminal	Vol	33	$VBDET2 = 20 \ \mu A$	0.0		0.2	V	
	output voltage	Vон	33	VBDET2 = $-20 \ \mu A$	OUT1 - 0.2		OUT1	V	
	CHARGE terminal	Vol	32	$CHARGE = 20 \ \mu A$	0.0		0.2	V	
	output voltage	Vон	32	$CHARGE = -20 \ \mu A$	OUT1 - 0.2		OUT1	V	
	FULL terminal	Vol	31	$FULL = 20 \ \mu A$	0.0		0.2	V	
	output voltage	Vон	31	$FULL = -20 \ \mu A$	OUT1 - 0.2		OUT1	V	
	SW1 ON resistance	Ron	23	SW1 = -600 μA, CONT5 = "H" level			500	Ω	
	XON delay	txon	11, 15, 16	RC1 = 1 μF	300	600	900	ms	

Parameter		Symbol	Din No	Conditions	Value			Unit
	Farameter	Symbol	FIII NO.	Conditions	Min.	Тур.	Max.	Unit
	Detection volt- age (rise)	Vsн	29	_		2.3*	_	V
POR	Detection volt- age (fall)	VsL	29		2.15	2.2	2.25	V
	Rise delay	t POR	29, 35	$C1 = 0.1 \ \mu F$	34	85	136	ms
~		VCCE	40	Initial power detected	2.62	2.75	2.87	V
op detection block		Vccd	40	Power supply dorop detected	2.38	2.50	2.61	V
	Detection	Vccr	40	Power supply recovery detected	3.35	3.50	3.65	V
	voitage	Vccf	40	Initial or power supply drop determined Ta = +25 °C	_	2.0*		V
ply dro	VccF temperature correlation	Vcct	40			-2.2	—	mV/ °C
Power sup	Power supply drop detection time	tDET1	34	$\label{eq:criterion} \begin{array}{l} CR1 = 10\;\muF,\\ CR1 = 1.8\;M\Omega \end{array}$	5	10	15	s
		tdet2	33	$\label{eq:criterion} \begin{array}{l} CR2 = 1.5 \ \muF, \\ CR2 = 1.8 \ M\Omega \end{array}$	0.75	1.5	2.25	s
	Standby supply current	Icc1	40	REG1 to REG4 : OFF, CONT5 = "L" level, ICONT = "L" level, VCC = 4.8 V		22	50	μA
Power supply control unit overall	Power-on invalid current (receiving standby)	Icc2	40	$\begin{array}{l} \text{REG3:OFF,}\\ \text{CONT5} = \text{``L'' level,}\\ \text{ICONT} = \text{``L'' level,}\\ \text{VCC} = 4.8 \text{ V,}\\ \text{OUT1} = -200 \ \mu\text{A,}\\ \text{OUT2} = -100 \ \mu\text{A,}\\ \text{OUT4} = -100 \ \mu\text{A,}\\ \text{Excluding OUT1, 2, 4 load current} \end{array}$		60	110	μΑ
	Power-on invalid current (call in progress)	Іссз	40	REG1 to REG4 : ON, CONT5 = "L" level, ICONT = "H" level, CONT2 = "L" level, VCC = 4.8 V , OUT1 = -70 mA , OUT2 = -50 mA , OUT3 = -70 mA , OUT4 = -60 mA , Excluding OUT1, 2, 4 load current		260	600	μΑ

*: Standard setting value

Parameter		Sym- bol	Pin No.	Conditions		Unit		
				Conditions	Min.	Тур.	Max.	
	Range of charging operation	VIN	1	Ta = −10 °C to +60 °C, BATSENSE = OPEN		_	5.5	V
			1	During charging	3.4	5.3	5.9	V
	Low voltage stop	Vadl	1	Ta = -10 °C to +60 °C, BATSENSE = OPEN/GND	2.70	3.05	3.40	V
	Over voltage stop	Vadh	1	Ta = −10 °C to +60 °C, BATSENSE = OPEN/GND	5.9	6.2	6.5	V
	Reference voltage	Vrefth	47	Ta = 0 °C to +50 °C, VREFTH = 0 to –1 mA	1.64	1.70	1.76	V
	Output current	IREFTH	47	$Ta = 0 \ ^{\circ}C$ to +50 $^{\circ}C$	-1			mA
	Output voltage	Vbat1	4	Ta = −10 °C to +60 °C, BATSEL = OPEN	4.070	4.112	4.154	V
unit		Vbat2	4	Ta = -10 °C to +60 °C, BATSEL = "L" level	4.170	4.212	4.254	V
control (VBPT	4	Overvoltage stop	4.257	4.327	4.397	V
		V_{BFT}	4	Rapid charging start voltage	3.015	3.115	3.215	V
ırge		VBRC	4	Recharging start voltage	3.877	3.942	4.007	V
Cha		VBPC	4	Preliminary charging start voltage	2.015	2.115	2.215	V
		ΔV B	4	Vbat2 – Vbrc	0.215	0.271	0.327	V
	Output current	Ігт	3, 4	Rapid charging current VBFT < VBAT < VBPT, RSENSE = 0.333Ω	565	590	615	mA
		СМР	3, 4	Charge control current V _{BFT} < VBAT < V _{BPT} , RSENSE = 0.333Ω	46	53	60	mA
		Ірс	3, 4	Preliminary charging current VBPC < VBAT < VBFT, RSENSE = 0.333Ω	72	80	95	mA
		Ireco	3, 4	Over discharge recovery charging current VBAT < V_{BPC} , VIN = 5.6 ± 0.2 V	0.8	2.1	10.0	mA

(Ta = +3 to +48 °C, VIN = 5.3 V, BATSENESE = GND)

Paramotor		Symbol	Pin No.	Conditions		Unit		
				Conditions	Min.	Тур.	Max.	Sint
	Timer	t⊧⊤	4	$\begin{array}{l} \text{ROSC} = 56 \text{ k}\Omega,\\ \text{COSC} = 100 \text{ pF} + 19 \text{ pF},\\ \text{Rapid charging}\\ \text{V}_{\text{BFT}} < \text{VBAT} < \text{V}_{\text{BPT}} \end{array}$	216	240	264	min
		tec	4	$\label{eq:ROSC} \begin{split} &ROSC = 56 \ k\Omega, \\ &COSC = 100 \ pF + 19 \ pF, \\ &Preliminary charging \\ &V_{BPC} < VBAT < V_{BFT} \end{split}$	14.4	16.0	17.6	min
		t reco	4	$\label{eq:ROSC} \begin{split} &ROSC = 56 \ k\Omega, \\ &COSC = 100 \ pF + 19 \ pF, \\ &Over \ discharge \ recovery \\ &charging \\ &VBAT < V_{BPC} \end{split}$	13.5	15.0	16.5	S
it	Initial determination delay	tod	1	ROSC = 56 kΩ, COSC = 100 pF + 19 pF, Ta = -10 °C to +60 °C	30	45	60	ms
Charge control uni	Full charge determination delay	tDIC	_	$\label{eq:ROSC} \begin{array}{l} ROSC = 56 \ k\Omega, \\ COSC = 100 \ pF + 19 \ pF \end{array}$	78	117	156	ms
	Overvoltage stop determination delay	tвоv		$\label{eq:ROSC} \begin{split} &ROSC = 56 \; k\Omega, \\ &COSC = 100 \; pF + 19 \; pF \end{split}$	0.30	0.46	0.62	s
	Charging restart determination delay	trc	_	$\label{eq:ROSC} \begin{split} &ROSC = 56 \; k\Omega, \\ &COSC = 100 \; pF + 19 \; pF \end{split}$	153	230	312	ms
	Battery tempera- ture detection	Тн∟т	48	VREFTH = 1.7 V , Ta = -10 °C to $+60 \text{ °C}$, 3 °C detected	1.154 0	1.189 3	1.223 6	∨ °C
		Тнѕυ	48	VREFTH = 1.7 V , Ta = $-10 \text{ °C to } +60 \text{ °C}$, 41 °C detected (initial)	0.539 38	0.571 41	0.601 45	∨ °C
		Тном1	48	VREFTH = 1.7 V , Ta = -10 °C to $+60 \text{ °C}$, 48 °C detected	0.463 45	0.488 48	0.511 51	∨ °C
		Тном1	48	VREFTH = 1.7 V , Ta = $-10 \text{ °C to } +60 \text{ °C}$, 41 °C detected (restart)	0.539 38	0.571 41	0.601 45	∨ °C
	BATSENSE terminal	VIL	43	Battery present	0.0		$0.3 \times VIN$	V
	input voltage	Vін	43	Battery not present	0.7 imes VIN		VIN	V
	(Continued)							

(Ta = +3 to +48 °C, VIN = 5.3 V, BATSENESE = GND)

				(Ta = +3 to +48 °C	C, VIN = 5.3	3 V, BAT	SENESE =	GND
Parameter		Symbol	Din No	Conditiono	Value			Unit
		Symbol	FIII NO.	Conditions	Min.	Тур.	Max.	Unit
	BATSEL terminal	VIL	46	4.2 V battery selected	0.0		$0.3 \times VIN$	V
-	input voltage	Vін	46	4.1 V battery selected	0.7 imes VIN		VIN	V
	LEDR terminal ON resistance	Ron	38	LEDR = 5 mA			80	Ω
	LEDG terminal ON resistance	Ron	37	LEDG = 5 mA			80	Ω
	LEDR, LEDG terminal output current	lo	37, 38	_	_		10	mA
	Supply current	Ivin	1	VIN = 5.8 V, Rapid charging		1.5	3.0	mA
Charge control unit	Leak current	Isen	3, 4	ISENSE+=ISENSE-=4.8 V, VCC = 4.8 V, VIN = CONT = GND			1	μΑ
	Test mode ISENSE- terminal clamp voltage	Vpr	4	BATSENSE = OPEN, V _{ADL} < VIN < V _{ADH} , Ta = -10 °C to +60 °C	4.75	4.88	5.01	V
	Test mode CONT terminal voltage	Vthr	2	BATSENSE = OPEN, V _{ADL} < VIN < V _{ADH} , VISENSE- = 2.5 V, CONT = 10 μ A		_	0.1	V
	Test mode response time	Rтор		BATSENSE = OPEN, external FET, gate capacitor < 1000 pF, Ta = -10 °C to +60 °C		_	100	μs
	BATSENSE response time	Rttovr		BATSENSE = GND \rightarrow OPEN or OPEN \rightarrow GND, external FET, gate capacitor< 1000 pF, Ta = -10 °C to +60 °C	_		30	ms
	Thermal protection	T _{H+}		Vadl < VIN < Vadh	125		158	°C

GND current vs. Power supply voltage

250

200

150

100

50

0

0

GND current IGND (µA)

Ta = +25[']°C

 $OUT1 = 36 \Omega$

 $OUT2 = 36 \ \Omega$ $OUT3 = 27 \Omega$

OUT4 = 42 Ω ICONT = "H"

CONT5 = "L"

1

2

Power supply voltage Vcc (V)

3

4

5

REG $1 \sim 4 = ON$

TYPICAL CHARACTERISTICS



Power supply current vs. Power supply voltage



Reference Voltage Block















FUNCTIONAL DESCRIPTION

1. Power Supply Control Unit

(1) Reference Voltage Block

The reference voltage circuit uses the voltage supplied from the VCC terminal (pin 40) and generates a temperature compensated reference voltage (1.23 V (Typ.)), for use as the reference voltage for the power supply control unit.

(2) Constant Voltage Control Block (REG1)

This constant voltage control block (REG1) uses the voltage supplied from the reference voltage and generates the output voltage (2.5 V) from the OUT1 terminal (pin 29).

An external load current can be obtained from the OUT1 terminal up to a maximum of 70 mA.

Also, by setting the ICONT terminal (pin 36) to "L" level the MB3893A can be placed in low current consumption (standby) mode. In standby mode, REG1 is On with a maximum output load of 500 μ A, and REG3 is Off. In this state, ripple rejection and noise levels are not assured.

(3) Constant Voltage Control Block (REG2)

This constant voltage control block (REG2) uses the voltage supplied from the reference voltage and generates the output voltage (1.8 V) from the OUT2 terminal (pin 30).

An external load current can be obtained from the OUT2 terminal up to a maximum of 50 mA.

Also, by setting the ICONT terminal (pin 36) to "L" level the MB3893A can be placed in low current consumption (standby) mode. In standby mode, REG2 is On with a maximum output load of 500 μ A, and REG3 is Off. In this state, ripple rejection and noise levels are not assured.

(4) Constant Voltage Control Block (REG3)

This constant voltage control block (REG3) uses the voltage supplied from the reference voltage and generates the output voltage from the OUT3 terminal (pin 27).

An external load current can be obtained from the OUT3 terminal up to a maximum of 70 mA. Also, the output voltage can be changed to 1.9V or 2.2 V by mask option.

(5) Constant Voltage Control Block (REG4)

This constant voltage control block (REG4) uses the voltage supplied from the reference voltage and generates the output voltage (2.5 V) from the OUT4 terminal (pin 22).

An external load current can be obtained from the OUT4 terminal up to a maximum of 60 mA.

Also, by setting the ICONT terminal (pin 36) to "L" level the MB3893A can be placed in low current consumption (standby) mode. In standby mode, REG4 is On with a maximum output load of 500 μ A, and REG3 is Off. In this state, ripple rejection and noise levels are not assured.

(6) VREF1M

This block takes the reference voltage (1.23 V (Typ.)) generated by the reference voltage block, and uses a voltage follower to produce a temperature compensated reference voltage (1.23 V (Typ.)) at the VREF1M terminal (pin 10).

Also, an external load current can be obtained from the VREF1M terminal up to a maximum of 1 mA.

(7) ON/OFF Control Block

This block controls regulator On/Off switching according to the voltage levels of the POFF terminal (pin 18), CONT2 terminal (pin 26), CONT5 terminal (pin 6), ICONT terminal (pin 36), DRST terminal (pin 5), XON terminal (pin 11), ONOFF1 terminal (pin 9), ONOFF2 terminal (pin 17), and CONT1 terminal (pin 14).

(8) POR Block

When the output voltage from the regulator (OUT1) exceeds 2.3 V (Typ.), the XRST terminal (pin 35) goes to "H" level following a delay time (85 ms (Typ.)) set by capacitors (0.1 μ F (Typ.)) connected between the C1 terminal (pin 7) and the GND1 terminal (pin 8) and GND2 terminal (pin 39). Also, when the regulator (OUT1) output voltage falls below 2.2 V ((Typ.)), the XRST terminal goes back to "L" level.

(9) Initial Power Supply Drop Detection 1

This block controls MB3893A operation when VCC startup occurs, at VCC voltage of 2.0V (Typ.) or greater. When VCC voltage exceeds 2.75V (Typ.) the VCONT terminal (pin 16) voltage goes to "H" level, and the regulated voltage is output from the OUT1 terminal (pin 29), OUT2 terminal (pin 30), and OUT4 terminal (pin 22). When VCC voltage falls below 3.1V (Typ.), the voltage at the OUT1, OUT2, and OUT4 terminals is outside of rated values. Then when VCC voltage falls below 2.5V (Typ.), the VCONT terminal (pin 16) voltage goes to "L" level, and the OUT1, OUT2, and OUT4 terminals go to "L" level (regulator "OFF" state). Hereafter this is referred to as "L" level. As long as the VCC voltage rises again before dropping below 2.0V (Typ.), the VCONT pin voltage will return to "H" level once VCC reaches 3.5 V (Typ.), and the regulated voltage is output from the OUT1, OUT2, and OUT4 terminals.

(10) Transient Power Supply Drop Detection 2

This block detects two types of power supply drop times according to the time constants CR1 and CR2, and produces the related output at the VBDET1 terminal (pin 34) and VBDET2 terminal (pin 33).

2. Charge Control Block

The charge control block checks VIN, battery voltage, and battery temperature before charging. If the results are within normal ranges, charging begins. The charging times and current levels are varied according to battery voltage. During charging, the VIN and battery temperature are monitored, and if either exceeds the normal range charging is stopped. Conditions are then monitored for a fixed time (16 min (Typ.)) and a resume charging/ abnormal termination determination is made.

The MB3893A also provides an overcharge protection function, as well as a function that stops charging when a rise in IC junction temperature is detected.

Once charging has stopped due to any of these abnormal conditions, it can be resumed by re-input of VIN, or by removing and replacing the battery.

(1) Constant Current/Constant Voltage Charging

The MB3893A applies a constant current charge according to the battery voltage level, selecting over discharge recovery charging (2.1 mA (Typ.)), preliminary charging (80 mA (Typ.)) or rapid charging (590 mA (Typ.)). Once battery voltage reaches 4.1 V (4.2 V), constant voltage charging is applied until the charge current falls to 53 mA (Typ.) at constant voltage.

(2) Timer Function

The timer switches the charging time according to the battery voltage level, between over discharge recovery charging (15 s (Typ.)), preliminary charging (16 min (Typ.)), and rapid charging (240 min (Typ.)).

(3) Temperature/AC Adapter Voltage Detection

This block detects the battery temperature and AC adapter voltage, and stops charging if either is outside of the normal charging range. If normal conditions are restored within a set time (16 min (Typ.)), charging is resumed, otherwise an abnormal termination is determined.

(4) Over-Charge Protection

If battery voltage exceeds 4.3 V (Typ.) this block determines an abnormal condition, and stops charging.

SETTING THE XON DELAY TIME

When the XON terminal (pin 11) voltage changes from "H" to "L" level, the VCONT signal (pin 16) rises. The time constant of the capacitor (C_{RC1}) and resistor (R_{RC1}) connected to the RC1 terminal (pin 15) determine the delay time before the rise of the VCONT signal (pin 16).

XON delay time : txon (ms) \Rightarrow 598.3 × C_{RC1} (μ F)

SETTING THE XRST DELAY TIME

The time constant of the capacitor (C_{C1}) connected to the C1 terminal (pin 7) determines the delay time between the rise of the OUT1 terminal (pin 29) voltage above 2.3 V (Typ.) and the rise of the XRST terminal (pin 35) voltage.

XRST delay time : tPOR (s) $\Rightarrow \frac{1.23 (V) \times C_{C1} (\mu F)}{1.45 (\mu A)}$

SETTING THE POWER SUPPLY DROP DETECTION TIME

When the VCC terminal (pin 40) voltage falls below 2.0 V (Typ.) the CR1 terminal (pin 12) and CR2 terminal (pin 13) are opened, and the capacitors (C_{CR1}, C_{CR2}) connected to the CR1 and CR2 terminals are discharged through the respective resistors (R_{CR1}, R_{CR2}). The discharge time (power supply drop detection time) of the CR1 and CR2 terminals can be set according to the time constants of the capacitors and resistors connected to the CR1 and CR2 terminals respectively, between 0.89 V (Typ.) to 0.51 V (Typ.).

Power supply drop detection time : t_{DET1} (s) \doteqdot $-C_{CR1}$ (μ F) \times R_{CR1} ($M\Omega$) \times In (0.51 (V) /0.89 (V)) t_{DET2} (s) \doteqdot $-C_{CR2}$ (μ F) \times R_{CR2} ($M\Omega$) \times In (0.51 (V) /0.89 (V))

BATTERY TEMPERATURE DETECTION

The battery temperature sensor uses the thermistor shown below. The thermistor temperature coefficient is set by the following formula.



SETTING THE OSCILLATOR PERIOD

The oscillator period is set by connecting a timing capacitor (Cosc) to the COSC terminal (pin 44), and a timing resistor (Rosc) to the ROSC terminal (pin 45).

Oscillator period : tosc (µs) \Rightarrow 1.073 × 10⁻³ × {Cosc (pF) + C_P (pF) } × Rosc (k Ω) C_P : Board capacitor \Rightarrow 19 (pF)

■ SETTING THE OVER DISCHARGE RECOVERY CHARGE TIME

When battery voltage is less than the preliminary charge start voltage (2.115 V (Typ.)), the over discharge recovery charge time is set by the following formula.

Over discharge recovery charge time : treco (s) \Rightarrow Tosc (s) $\times 2^{21}$

PRELIMINARY CHARGE TIME

When battery voltage is higher than the preliminary charge start voltage (2.115 V (Typ.)), and lower than the rapid charge start voltage (3.115 V (Typ.)), the preliminary charge time is set by the following formula.

Preliminary charge time : tPC (min) $\Rightarrow \frac{\text{tosc } (s) \times 2^{27}}{60}$

RAPID CHARGE TIME

When battery voltage is higher then the rapid charge start voltage (3.115 V (Typ.)), and lower than the overvoltage stop voltage (4.327 V (Typ.)), the rapid charging time is determined by the following formula.

Rapid charging time : tFT (min) $\Rightarrow \frac{\text{tosc } (s) \times (2^{27} + 2^{28} + 2^{29} + 2^{30})}{60}$

POWER SUPPLY CONTROL UNIT TIMING CHART

1. Power Supply Drop Detection 1

As Figure 1 shows, there is a "don't care zone" where VCC voltage is below 2 V. When VCC voltage is above VCCE voltage (2.75 V (Typ.)), the VCONT terminal (pin 16) goes to "H" level, and after a delay time (tR) the OUT1 terminal (pin 29), the OUT2 terminal (pin 30), and the OUT4 terminal (pin 22) output their regulated voltages. When VCC voltage falls below VCCD voltage (2.50 V (Typ.)), a power supply drop detection is determined and the VCONT terminal goes to "L" level, and therefore the OUT1, OUT2, and OUT4 terminals also go to "L" level. If the VCC voltage rises again before falling below 2 V (Typ.), the OUT1, OUT2, and OUT4 terminals will once again output their regulated voltages once VCC exceeds the VCCR voltage (3.50 V (Typ.)).



2. Delayed ON Input Operation (XON)

As Figure 2 shows, When the XON terminal (pin 11) changes from "H" to "L" level, the capacitor connected to the RC1 terminal (pin 15) starts to charge. After the delay time (t_{XON} : 600ms (Typ.)), once the RC1 terminal exceeds the internal threshold voltage the VCONT terminal (pin 16) goes to "H" level, and the OUT1 (pin 29), OUT2 (pin 30), OUT3 (pin 27), and OUT4 (pin 22) terminals then output their respective regulated voltages after a delay time (t_{R1}). Note however that for the OUT3 terminal to output its regulated voltage, it is necessary for the CONT2 terminal (pin 26) to be at "L" level. Also, for the XON terminal to return from "L" level to "H" level, a delay time (t_{XON} : 600 ms (Typ.)) is required.



3. CONT1 Input Operation

As Figure 3 shows, when the CONT1 terminal (pin 14) goes from "H" to "L" level, the VCONT terminal (pin 16) goes to "H" level, and the OUT1 (pin 29), OUT2 (pin 30), OUT3 (pin 27), and OUT4 (pin 22) terminals then output their respective regulated voltages after a delay time (t_{R1}). Note however that for the OUT3 terminal to output its regulated voltage, it is necessary for the CONT2 terminal (pin 26) to be at "L" level. Also once the OUT1, OUT2, OUT3, and OUT4 terminals have started to output their regulated voltages, the voltage at the OUT1, OUT2, OUT3, and OUT4 terminals will not change even if the CONT1 terminal goes from "L" to "H" level, or from "H" level to "L" level.



4. POFF Input Operation

As Figure 4 shows, once when the POFF terminal (pin 18) goes to "H" level, then after a delay interval (0 < delay < 100 μ s) the VCONT terminal (pin 16) goes to "L" level, and the OUT1 (pin 29), OUT2 (pin 30), and OUT4 (pin 22) terminals then after a delay interval (t) go to "L" level. Also, a minimum of 10 μ s is required to set the POFF signal to "H" level.



5. CONT2 Input Operation

As Figure 5 shows, when the CONT2 terminal (pin 26) goes from "H" to "L" level, the OUT3 terminal (pin 27) after a delay time (t_{R1}) outputs its regulated voltage. When the CONT2 terminal goes from "L" to "H" level, then the OUT3 terminal returns to "L" level after the required fall time (t).



6. ONOFF1, 2 Input Operation

As Figure 6 shows, when the ONOFF1 terminal (pin 9) goes from "L" level to "H" level, the VCONT terminal (pin 16) goes to "H" level, and the OUT1 (pin 29), OUT2 (pin 30), OUT3 (pin 27), and OUT4 (pin 22) terminals output their respective regulated voltages.

The next time the POFF terminal (pin 18) goes from "L" level to "H" level, the VCONT terminal (pin 16) goes to "L" level, and the OUT1 (pin 29), OUT2 (pin 30), and OUT4 (pin 22) terminals go to "L" level. Then when the ONOFF2 terminal (pin 17) goes from "L" level to "H" level, the VCONT terminal returns to "H" level, and the OUT1, OUT2, OUT3 and OUT4 terminals output their respective regulated voltages.

The next time the POFF terminal goes from "L" level to "H" level, the VCONT terminal goes to "L" level, and the OUT1, OUT2, and OUT4 terminals go to "L" level. Then when the ONOFF1 terminal goes from "L" level to "H" level, the VCONT terminal returns to "H" level, and the OUT1, OUT2 and OUT4 terminals output their respective regulated voltages.

The next time the POFF terminal goes from "L" level to "H" level, the VCONT terminal goes to "L" level, and the OUT1, OUT2, and OUT4 terminals go to "L" level. Then when the ONOFF2 terminal goes from "H" level to "L" level, the VCONT terminal returns to "H" level, and the OUT1, OUT2 and OUT4 terminals output their respective regulated voltages.

The next time the POFF terminal goes from "L" level to "H" level, the VCONT terminal goes to "L" level, and the OUT1, OUT2, and OUT4 terminals go to "L" level.



7. Power-On Reset (OUT1)

As Figure 7 shows, when the OUT1 terminal (pin 29) exceeds 2.3 V (Typ.), then after a delay interval (85 ms (Typ.)) the XRST terminal (pin 35) goes to "H" level.

When the OUT1 terminal falls back below 2.2 V (Typ.), the XRST terminal returns to "L" level.



8. ICONT Input Operation

As Figure 8 shows, when the VCONT terminal (pin 16) goes from "L" level to "H" level, the OUT1 terminal (pin 29) outputs its regulated voltage. Then, after a delay interval (85 ms (Typ.)) the XRST terminal (pin 35) goes to "H" level.

If after the XRST terminal has gone to "H" level the ICONT terminal (pin 36) goes to "L" level, the MB3893A goes into standby mode, reducing the IC internal current consumption. When the ICONT terminal returns to "H" level normal operation is restored.

When the VCONT terminal goes from "H" level to "L" level, the OUT1 terminal goes to "L" level. At this time the XRST terminal also goes to "L" level.



9. Power Supply Drop Detector 2 (Initial power supply detector/power supply drop detector) a) $t > 10 \ s$

The MB3893A power supply drop detection times are set to t_{DET1} (10 s (Typ.)) and t_{DET2} (1.5 s (Typ.)) so that, as shown in Figure 9(a), when VCC goes from "H" level to "L" level, the OUT1 (pin 29), OUT2 (pin 30), and OUT4 (pin 22) terminals go to "L" level, and the XRST terminal (pin 35) also goes to "L" level. At this time, the VBDET1 terminal (pin 34) and VBDET2 terminal (pin 33) also go to "L" level. When VCC drops for a fixed interval (t > 10 s), and then returns to "H" level, the OUT1, OUT2, and OUT4 terminals after a delay interval (t_{R2}) output their regulated voltages, and the XRST terminal after a delay time (t_{POR}) goes to "H" level. During the interval between the VCC drop and XRST terminal return to "H" level the VBDET1 terminal and VBDET2 terminal are in undefined state. Also once the XRST terminal returns to "H" level the VBDET1 terminal is at "L" level and the VBDET2 terminal is at "H" level. At this time, if the DRST terminal (pin 5) goes to "H" level, the VBDET1 terminal also goes to "H" level. Note that the DRST terminal must be at "H" level for at least an interval of 10 μ s.



b) 1.5 < t < 0 s

The MB3893A power supply drop detection times are set to t_{DET1} (10 s (Typ.)) and t_{DET2} (1.5 s (Typ.)) so that, as shown in Figure 9(b), when VCC goes from "H" level to "L" level, the OUT1 (pin 29), OUT2 (pin 30), and OUT4 (pin 22) terminals go to "L" level, and the XRST terminal (pin 35) also goes to "L" level. At this time, the VBDET1 terminal (pin 34) and VBDET2 terminal (pin 33) also go to "L" level. When VCC drops for a fixed interval (1.5 s < t < 10 s), and then returns to "H" level, the OUT1, OUT2, and OUT4 terminals after a delay interval (t_{R2}) output their regulated voltages, and the XRST terminal after a delay time (t_{POR}) goes to "H" level. During the interval between the VCC drop and XRST terminal return to "H" level the VBDET1 terminal is at "H" level and the VBDET2 terminal is also at "H" level. At this time, if the DRST terminal (pin 5) goes to "H" level, the VBDET1 and VBDET2 terminal is at "H" level. Note that the DRST terminal must be at "H" level for at least an interval of 10 μ s.



c) t < 1.5 s

The MB3893A power supply drop detection times are set to t_{DET1} (10 s (Typ.)) and t_{DET2} (1.5 s (Typ.)) so that, as shown in Figure 9(c), when VCC goes from "H" level to "L" level, the OUT1 (pin 29), OUT2 (pin 30), and OUT4 (pin 22) terminals go to "L" level, and the XRST terminal (pin 35) also goes to "L" level. At this time, the VBDET1 terminal (pin 34) and VBDET2 terminal (pin 33) also go to "L" level. When VCC drops for a fixed interval (t < 1.5 s), and then returns to "H" level, the OUT1, OUT2, and OUT4 terminals after a delay interval (t_{R2}) output their regulated voltages, and the XRST terminal after a delay time (t_{POR}) goes to "H" level. During the interval between the VCC drop and XRST terminal return to "H" level the VBDET1 terminal and VBDET2 terminal are in undefined state. Also once the XRST terminal returns to "H" level the VBDET1 terminal is at "H" level and the VBDET2 terminal is at "L" level. At this time, if the DRST terminal (pin 5) goes to "H" level, the VBDET2 terminal goes to "H" level. Note that the DRST terminal must be at "H" level for at least an interval of 10 μ s.



CHARGE CONTROL UNIT OPERATION FLOWCHART



*2 : The 80 mA current is supplied from the external P-ch MOSFET (77.9 mA) plus the IC internal current of 2.1 mA.

■ CHARGE CONTROL UNIT LED OPERATION TABLE

• FULL, CHARGE, LEDR Operation Table

Operating condition OUT1		Qualitat	Signal pin				
		Switch	FULL	CHARGE	LE	DR	
		OUT1	ON	ON	ON	ON/OFF	
LEDEN				—	Н	L	
No operation VIN OFF VIN ON, BATSI			Н	н			
		N, BATSENSE open		Н	н	Н	н
Over discharge recovery charging 2.1 mA				_		L	
Preliminary chargin	ig 80 mA			Н	L	Н	L
Rapid charging 590) mA			Н	L	Н	L
Charging complete	d			L	Н	Н	н
3.942 V recharging				Н	L	Н	L
		2.1 mA			—		н
Temperature detection		80 mA		Н	н	Н	н
		590 mA		Н	н	Н	н
		2.1 mA			—		н
Temperature detec	tion reater	80 mA		Н	н	Н	н
		590 mA		Н	н	Н	н
VIN Low < 3.05 V VCC < VIN		2.1 mA			—		н
		80 mA		Н	н	Н	н
		590 mA		Н	н	Н	н
VIN High > 6.20 V		2.1 mA					н
		80 mA		Н	н	Н	н
		590 mA		Н	н	Н	н
		15 s Time out			—		L↔H
		16 min Time out		Н	L↔H	Н	L↔H
Battery abnormal		VBAT < 3.942 V 240 min Time out		н	L↔H	н	L↔H
		VBAT 240 m	> 3.942 V in Time out	L	н	Н	н
		VBAT > 4.327 V		Н	L↔H	Н	L↔H

LEDR, CHARGE = $L \leftrightarrow H$: Blinking, LEDR = L : ON, H : OFF

LEDEN, FULL, CHARGE : Power supply is OUT1, therefore undefined when OUT1 = OFF. OUT1=OFF during over discharge recovery charging (2.1 mA) and 15 s time out

• LEDG Operation Table

LED	LEDG
L	Н
Н	L

LEDG = L : ON, H : OFF

LED, LEDG: Power supply is OUT1, therefore undefined when OUT1 = OFF.

ABOUT CAPACITOR CONNECTED TO VCC TERMINAL

When the VCC voltage exceeds 2.75 V (Typ.), the VCONT terminal (pin 16) goes to "H" level, and the OUT1 (pin 29), OUT2 (pin 30), and OUT4 (pin 22) terminals rise. When each of these respective OUT terminals rises, a rush current flows to the capacitor connected to that OUT terminal. At this time the internal impedance of the battery causes VCC to drop, and if VCC voltage goes below 2.5 V (Typ.), the OUT terminal voltage returns to "L" level (regulator OFF mode). It is necessary to set the capacitor connected between VCC and GND taking into consideration the internal impedance of the battery, so that the VCC drop does not go below 2.5 V.

■ APPLICATION EXAMPLE



■ USAGE PRECAUTIONS

1. Never use settings exceeding maximum rated conditions.

Exceeding maximum rated conditions may cause permanent damage to the LSI. Also, it is recommended that recommended operating conditions be observed in normal use. Exceeding recommended operating conditions may adversely affect LSI reliability.

2. Use this device within recommended operating conditions.

Recommended operating conditions are values within which normal LSI operation is warranted. Standard electrical characteristics are warranted within the range of recommended operating conditions and within the listed conditions for each parameter.

3. Printed circuit board ground lines should be set up with consideration for common impedance.

4. Take appropriate static electricity measures.

- Containers for semiconductor materials should have anti-static protection or be made of conductive material.
- After mounting, printed circuit boards should be stored and shipped in conductive bags or containers.
- Work platforms, tools, and instruments should be properly grounded.
- Working personal should be grounded with resistance of 250 k Ω to 1 M Ω between body and ground.

5. Do not apply negative voltages.

The use of negative voltages below -0.3 V may create parasitic transistors on LSI lines, which can cause abnormal operation.

ORDERING INFORMATION

Part number	Package	Remarks
MB3893APFV	48-pin plastic LQFP (FPT-48P-M05)	
MB3893APFT	48-pin plastic TQFP (FPT-48P-M24)	







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