

Data sheet acquired from Harris Semiconductor SCHS204J

February 1998 - Revised December 2003

# High-Speed CMOS Logic Phase-Locked Loop with VCO

#### Features

- Operating Frequency Range
  - Up to 18MHz (Typ) at  $V_{CC} = 5V$
  - Minimum Center Frequency of 12MHz at V<sub>CC</sub> = 4.5V
- · Choice of Three Phase Comparators
  - EXCLUSIVE-OR
  - Edge-Triggered JK Flip-Flop
  - Edge-Triggered RS Flip-Flop
- Excellent VCO Frequency Linearity
- VCO-Inhibit Control for ON/OFF Keying and for Low Standby Power Consumption
- Minimal Frequency Drift
- Operating Power Supply Voltage Range

  - Digital Section ......2V to 6V
- Fanout (Over Temperature Range)
  - Standard Outputs......10 LSTTL Loads
  - Bus Driver Outputs ...... 15 LSTTL Loads
- Wide Operating Temperature Range . . . -55°C to 125°C
- Balanced Propagation Delay and Transition Times
- Significant Power Reduction Compared to LSTTL Logic ICs
- HC Types
  - 2V to 6V Operation
  - High Noise Immunity:  $N_{IL}$  = 30%,  $N_{IH}$  = 30% of  $V_{CC}$  at  $V_{CC}$  = 5V
- HCT Types
  - 4.5V to 5.5V Operation
  - Direct LSTTL Input Logic Compatibility,
     V<sub>IL</sub>= 0.8V (Max), V<sub>IH</sub> = 2V (Min)
  - CMOS Input Compatibility,  $I_I \le 1\mu A$  at VOL, VOH

### **Applications**

- FM Modulation and Demodulation
- · Frequency Synthesis and Multiplication
- Frequency Discrimination
- Tone Decoding
- Data Synchronization and Conditioning
- Voltage-to-Frequency Conversion
- Motor-Speed Control

#### Description

The 'HC4046A and 'HCT4046A are high-speed silicon-gate CMOS devices that are pin compatible with the CD4046B of the "4000B" series. They are specified in compliance with JEDEC standard number 7.

The 'HC4046A and 'HCT4046A are phase-locked-loop circuits that contain a linear voltage-controlled oscillator (VCO) and three different phase comparators (PC1, PC2 and PC3). A signal input and a comparator input are common to each comparator.

The signal input can be directly coupled to large voltage signals, or indirectly coupled (with a series capacitor) to small voltage signals. A self-bias input circuit keeps small voltage signals within the linear region of the input amplifiers. With a passive low-pass filter, the 4046A forms a second-order loop PLL. The excellent VCO linearity is achieved by the use of linear op-amp techniques.

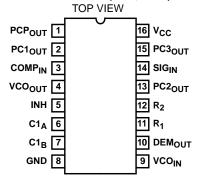
#### **Ordering Information**

PART NUMBER	TEMP. RANGE ( <sup>O</sup> C)	PACKAGE
CD54HC4046AF3A	-55 to 125	16 Ld CERDIP
CD54HCT4046AF3A	-55 to 125	16 Ld CERDIP
CD74HC4046AE	-55 to 125	16 Ld PDIP
CD74HC4046AM	-55 to 125	16 Ld SOIC
CD74HC4046AMT	-55 to 125	16 Ld SOIC
CD74HC4046AM96	-55 to 125	16 Ld SOIC
CD74HC4046ANSR	-55 to 125	16 Ld SOP
CD74HC4046APWR	-55 to 125	16 Ld TSSOP
CD74HC4046APWT	-55 to 125	16 Ld TSSOP
CD74HCT4046AE	-55 to 125	16 Ld PDIP
CD74HCT4046AM	-55 to 125	16 Ld SOIC
CD74HCT4046AMT	-55 to 125	16 Ld SOIC
CD74HCT4046AM96	-55 to 125	16 Ld SOIC

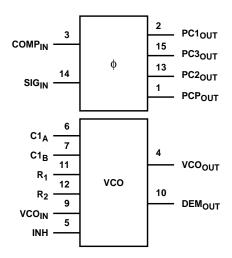
NOTE: When ordering, use the entire part number. The suffixes 96 and R denote tape and reel. The suffix T denotes a small-quantity reel of 250.

# **Pinout**

CD54HC4046A, CD54HCT4046A (CERDIP) CD74HC4046A (PDIP, SOIC, SOP, TSSOP) CD74HCT4046A (PDIP, SOIC)



# Functional Diagram



# Pin Descriptions

PIN NUMBER	SYMBOL	NAME AND FUNCTION
1	PCP <sub>OUT</sub>	Phase Comparator Pulse Output
2	PC1 <sub>OUT</sub>	Phase Comparator 1 Output
3	COMPIN	Comparator Input
4	VCO <sub>OUT</sub>	VCO Output
5	INH	Inhibit Input
6	C1 <sub>A</sub>	Capacitor C1 Connection A
7	C1 <sub>B</sub>	Capacitor C1 Connection B
8	GND	Ground (0V)
9	VCO <sub>IN</sub>	VCO Input
10	DEM <sub>OUT</sub>	Demodulator Output
11	R <sub>1</sub>	Resistor R1 Connection
12	R <sub>2</sub>	Resistor R2 Connection
13	PC2 <sub>OUT</sub>	Phase Comparator 2 Output
14	SIG <sub>IN</sub>	Signal Input
15	PC3 <sub>OUT</sub>	Phase Comparator 3 Output
16	V <sub>CC</sub>	Positive Supply Voltage

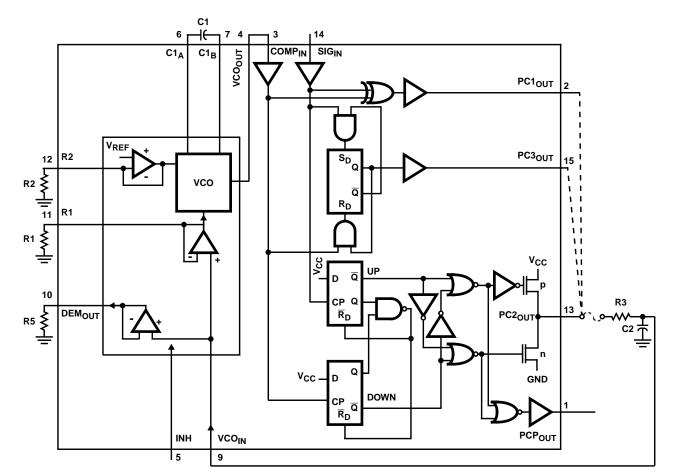


FIGURE 1. LOGIC DIAGRAM

#### General Description

#### **VCO**

The VCO requires one external capacitor C1 (between C1<sub>A</sub> and C1<sub>B</sub>) and one external resistor R1 (between R<sub>1</sub> and GND) or two external resistors R1 and R2 (between R<sub>1</sub> and GND, and R<sub>2</sub> and GND). Resistor R1 and capacitor C1 determine the frequency range of the VCO. Resistor R2 enables the VCO to have a frequency offset if required. See logic diagram, Figure 1.

The high input impedance of the VCO simplifies the design of low-pass filters by giving the designer a wide choice of resistor/capacitor ranges. In order not to load the low-pass filter, a demodulator output of the VCO input voltage is provided at pin 10 (DEMOUT). In contrast to conventional techniques where the DEMOUT voltage is one threshold voltage lower than the VCO input voltage, here the DEMOUT voltage equals that of the VCO input. If DEMOUT is used, a load resistor (RS) should be connected from DEMOUT to GND; if unused, DEMOUT should be left open. The VCO output (VCO<sub>OUT</sub>) can be connected directly to the comparator input (COMPIN), or connected via a frequencydivider. The VCO output signal has a specified duty factor of 50%. A LOW level at the inhibit input (INH) enables the VCO and demodulator, while a HIGH level turns both off to minimize standby power consumption.

#### **Phase Comparators**

The signal input (SIG<sub>IN</sub>) can be directly coupled to the self-biasing amplifier at pin 14, provided that the signal swing is between the standard HC family input logic levels. Capacitive coupling is required for signals with smaller swings.

#### Phase Comparator 1 (PC1)

This is an Exclusive-OR network. The signal and comparator input frequencies  $(f_i)$  must have a 50% duty factor to obtain the maximum locking range. The transfer characteristic of PC1, assuming ripple  $(f_r = 2f_j)$  is suppressed, is:

 $V_{DEMOUT} = (V_{CC}/\pi)$  ( $\phi SIG_{IN} - \phi COMP_{IN}$ ) where  $V_{DEMOUT}$  is the demodulator output at pin 10;  $V_{DEMOUT} = V_{PC1OUT}$  (via low-pass filter).

The average output voltage from PC1, fed to the VCO input via the low-pass filter and seen at the demodulator output at pin 10 (VDEMOUT), is the resultant of the phase differences of signals (SIGIN) and the comparator input (COMPIN) as shown in Figure 2. The average of VDEM is equal to 1/2 VCC when there is no signal or noise at SIGIN, and with this input the VCO oscillates at the center frequency (fo). Typical waveforms for the PC1 loop locked at fo are shown in Figure 3.

The frequency capture range  $(2f_C)$  is defined as the frequency range of input signals on which the PLL will lock if it was initially out-of-lock. The frequency lock range  $(2f_L)$  is defined as the frequency range of input signals on which the loop will stay locked if it was initially in lock. The capture range is smaller or equal to the lock range.

With PC1, the capture range depends on the low-pass filter characteristics and can be made as large as the lock range. This configuration retains lock behavior even with very noisy input signals. Typical of this type of phase comparator is that it can lock to input frequencies close to the harmonics of the VCO center frequency.

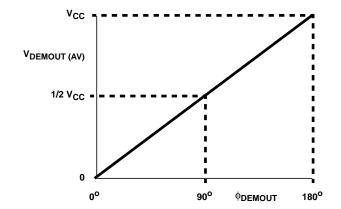


FIGURE 2. PHASE COMPARATOR 1: AVERAGE OUTPUT VOLTAGE vs INPUT PHASE DIFFERENCE:  $V_{DEMOUT} = V_{PC1OUT} = (V_{CC}/\pi) (\phi SIG_{IN} - \phi COMP_{IN}); \phi_{DEMOUT} = (\phi SIG_{IN} - \phi COMP_{IN})$ 

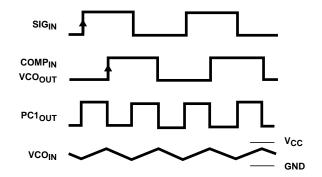


FIGURE 3. TYPICAL WAVEFORMS FOR PLL USING PHASE COMPARATOR 1, LOOP LOCKED AT  $f_0$ 

#### Phase Comparator 2 (PC2)

This is a positive edge-triggered phase and frequency detector. When the PLL is using this comparator, the loop is controlled by positive signal transitions and the duty factors of  ${\sf SIG_{IN}}$  and  ${\sf COMP_{IN}}$  are not important. PC2 comprises two D-type flip-flops, control-gating and a three-state output stage. The circuit functions as an up-down counter (Figure 1) where  ${\sf SIG_{IN}}$  causes an up-count and  ${\sf COMP_{IN}}$  a down-count. The transfer function of PC2, assuming ripple (fr = fi) is suppressed, is:

The average output voltage from PC2, fed to the VCO via the low-pass filter and seen at the demodulator output at pin 10 ( $V_{DEMOUT}$ ), is the resultant of the phase differences of  $SIG_{IN}$  and  $COMP_{IN}$  as shown in Figure 4. Typical waveforms for the PC2 loop locked at  $f_0$  are shown in Figure 5.

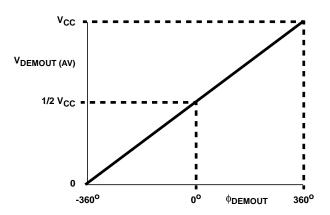


FIGURE 4. PHASE COMPARATOR 2: AVERAGE OUTPUT VOLTAGE vs INPUT PHASE DIFFERENCE: VDEMOUT = VPC2OUT

=  $(V_{CC}/4\pi)$  ( $\phi$ SIG<sub>IN</sub> -  $\phi$ COMP<sub>IN</sub>);  $\phi$ DEMOUT =  $(\phi$ SIG<sub>IN</sub> -  $\phi$ COMP<sub>IN</sub>)

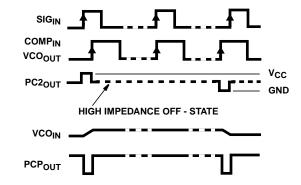


FIGURE 5. TYPICAL WAVEFORMS FOR PLL USING PHASE COMPARATOR 2, LOOP LOCKED AT  $f_{\rm O}$ 

When the frequencies of SIG<sub>IN</sub> and COMP<sub>IN</sub> are equal but the phase of SIG<sub>IN</sub> leads that of COMP<sub>IN</sub>, the p-type output driver at PC2<sub>OUT</sub> is held "ON" for a time corresponding to the phase difference ( $\phi_{DEMOUT}$ ). When the phase of SIG<sub>IN</sub> lags that of COMP<sub>IN</sub>, the n-type driver is held "ON".

When the frequency of  $SIG_{IN}$  is higher than that of  $COMP_{IN}$ , the p-type output driver is held "ON" for most of the input signal cycle time, and for the remainder of the cycle both n- and p-type drivers are "OFF" (three-state). If the  $SIG_{IN}$  frequency is lower than the  $COMP_{IN}$  frequency, then it is the n-type driver that is held "ON" for most of the cycle. Subsequently, the voltage at the capacitor (C2) of the low-pass filter connected to  $PC2_{OUT}$  varies until the signal and comparator inputs are equal in both phase and

frequency. At this stable point the voltage on C2 remains constant as the PC2 output is in three-state and the VCO input at pin 9 is a high impedance. Also in this condition, the signal at the phase comparator pulse output (PCP<sub>OUT</sub>) is a HIGH level and so can be used for indicating a locked condition.

Thus, for PC2, no phase difference exists between  $SIG_{IN}$  and  $COMP_{IN}$  over the full frequency range of the VCO. Moreover, the power dissipation due to the low-pass filter is reduced because both p- and n-type drivers are "OFF" for most of the signal input cycle. It should be noted that the PLL lock range for this type of phase comparator is equal to the capture range and is independent of the low-pass filter. With no signal present at  $SIG_{IN}$ , the VCO adjusts, via PC2, to its lowest frequency.

#### Phase Comparator 3 (PC3)

This is a positive edge-triggered sequential phase detector using an RS-type flip-flop. When the PLL is using this comparator, the loop is controlled by positive signal transitions and the duty factors of  $SIG_{IN}$  and  $COMP_{IN}$  are not important. The transfer characteristic of PC3, assuming ripple ( $f_r = f_i$ ) is suppressed, is:

 $V_{DEMOUT} = (V_{CC}/2p)$  (fSIG<sub>IN</sub> - fCOMP<sub>IN</sub>) where  $V_{DEMOUT}$  is the demodulator output at pin 10;  $V_{DEMOUT} = V_{PC3OUT}$  (via low-pass filter).

The average output from PC3, fed to the VCO via the low-pass filter and seen at the demodulator at pin 10 ( $V_{DEMOUT}$ ), is the resultant of the phase differences of SIGIN and COMPIN as shown in Figure 6. Typical waveforms for the PC3 loop locked at  $f_0$  are shown in Figure 7.

The phase-to-output response characteristic of PC3 (Figure 6) differs from that of PC2 in that the phase angle between SIG<sub>IN</sub> and COMP<sub>IN</sub> varies between 0° and 360° and is 180° at the center frequency. Also PC3 gives a greater voltage swing than PC2 for input phase differences but as aconsequence the ripple content of the VCO input signal is higher. With no signal present at SIG<sub>IN</sub>, the VCO adjusts, via PC3, to its highest frequency.

The only difference between the HC and HCT versions is the input level specification of the INH input. This input disables the VCO section. The comparator's sections are identical, so that there is no difference in the  ${\rm SIG_{IN}}$  (pin 14) or  ${\rm COMP_{IN}}$  (pin 3) inputs between the HC and the HCT versions.

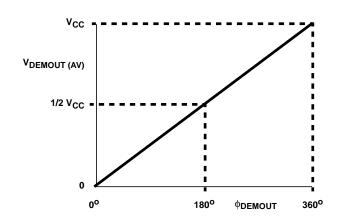


FIGURE 6. PHASE COMPARATOR 3: AVERAGE OUTPUT VOLTAGE vs INPUT PHASE DIFFERENCE:

 $\begin{aligned} & V_{DEMOUT} = V_{PC3OUT} \\ & = (V_{CC}/2\pi) \text{ } (\phi \text{SIG}_{\text{IN}} - \phi \text{COMP}_{\text{IN}}); \\ & \phi_{DEMOUT} = (\phi \text{SIG}_{\text{IN}} - \phi \text{COMP}_{\text{IN}}) \end{aligned}$ 

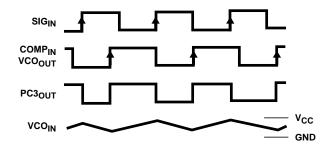


FIGURE 7. TYPICAL WAVEFORMS FOR PLL USING PHASE COMPARATOR 3, LOOP LOCKED AT  $f_{\rm o}$ 

#### 

 2V
 1000ns (Max)

 4.5V
 500ns (Max)

 6V
 400ns (Max)

#### **Thermal Information**

Package Thermal Impedance, $\theta_{JA}$ (see Note 1):
E (PDIP) Package
M (SOIC) Package73°C/W
NS (SOP) Package
PW (TSSOP) Package
Maximum Junction Temperature
Maximum Storage Temperature Range65°C to 150°C
Maximum Lead Temperature (Soldering 10s)300°C
(SOIC - Lead Tips Only)

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

#### NOTE:

1. The package thermal impedance is calculated in accordance with JESD 51-7.

#### **DC Electrical Specifications**

Supply Voltage Range, V<sub>CC</sub>

Input Rise and Fall Time

		TES CONDI		V <sub>CC</sub>		25°C		-40°C 1	O 85°C	-55°C T	O 125°C	
PARAMETER	SYMBOL	V <sub>I</sub> (V)	I <sub>O</sub> (mA)	(V)	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNITS
HC TYPES												
VCO SECTION												
INH High Level Input	V <sub>IH</sub>	-	-	3	2.1	•	-	2.1	-	2.1	-	V
Voltage				4.5	3.15	ı	-	3.15	-	3.15	-	V
				6	4.2	ı	-	4.2	-	4.2	-	V
INH Low Level Input	V <sub>IL</sub>	-	-	3	-	-	0.9	-	0.9	-	0.9	V
Voltage				4.5	-	-	1.35	-	1.35	-	1.35	V
				6	-	-	1.8	-	1.8	-	1.8	V
VCO <sub>OUT</sub> High Level	V <sub>OH</sub>	V <sub>IH</sub> or V <sub>IL</sub>	-0.02	3	2.9	-	-	2.9	-	2.9	-	V
Output Voltage CMOS Loads			-0.02	4.5	4.4	-	-	4.4	-	4.4	-	V
OWOO Loads			-0.02	6	5.9	-	-	5.9	-	5.9	-	V
VCO <sub>OUT</sub> High Level	]		-	-	-	-	-	-	-	-	-	V
Output Voltage TTL Loads			-4	4.5	3.98	-	-	3.84	-	3.7	-	V
TTE Eddus			-5.2	6	5.48	-	-	5.34	-	5.2	-	V
VCO <sub>OUT</sub> Low Level	V <sub>OL</sub>	V <sub>IH</sub> or V <sub>IL</sub>	0.02	2	-	-	0.1	-	0.1	-	0.1	V
Output Voltage CMOS Loads			0.02	4.5	-	-	0.1	-	0.1	-	0.1	V
OWOO Loads			0.02	6	-	-	0.1	-	0.1	-	0.1	V
VCO <sub>OUT</sub> Low Level			-	-	-	-	-	-	-	-	-	V
Output Voltage TTL Loads			4	4.5	-	-	0.26	-	0.33	-	0.4	V
TTE LUAUS			5.2	6	-	-	0.26	-	0.33	-	0.4	V
C1A, C1B Low Level	V <sub>OL</sub>	V <sub>IL</sub> or V <sub>IH</sub>	4	4.5	-	-	0.40	-	0.47	-	0.54	V
Output Voltage (Test Purposes Only)			5.2	6	-	-	0.40	-	0.47	-	0.54	V

# DC Electrical Specifications (Continued)

		CONDI		V <sub>CC</sub>		25°C		-40°C 1	го 85°C	-55°C T	O 125°C	
PARAMETER	SYMBOL	V <sub>I</sub> (V)	I <sub>O</sub> (mA)	(V)	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNITS
INH VCO <sub>IN</sub> Input Leakage Current	Ι <sub>Ι</sub>	V <sub>CC</sub> or GND	-	6	-	-	±0.1	-	±1	-	±1	μΑ
R1 Range (Note 2)	-	-	-	4.5	3	-	300	-	-	-	-	kΩ
R2 Range (Note 2)	-	-	-	4.5	3	-	300	-	-	-	-	kΩ
C1 Capacitance	-	-	-	3	-	-	No	-	-	-	-	pF
Range				4.5	-	-	Limit	-	-	-	-	pF
				6	-	-	1	-	-	-	-	pF
VCO <sub>IN</sub> Operating	-	Over the	range	3	1.1	-	1.9	-	-	-	-	V
Voltage Range		specified f		4.5	1.1	-	3.2	-	-	-	-	V
		10, and (Note	34 - 37	6	1.1	-	4.6	-	-	-	-	V
PHASE COMPARATO	R SECTIO	N										
SIG <sub>IN</sub> , COMP <sub>IN</sub>	V <sub>IH</sub>	-	-	2	1.5	-	-	1.5	-	1.5	-	V
DC Coupled High-Level Input				4.5	3.15	-	-	3.15	-	3.15	-	V
Voltage				6	4.2	-	-	4.2	-	4.2	-	V
SIG <sub>IN</sub> , COMP <sub>IN</sub>	V <sub>IL</sub>	-	-	2	-	-	0.5	-	0.5	-	0.5	V
DC Coupled				4.5	-	-	1.35	-	1.35	-	1.35	V
Low-Level Input Voltage				6	-	-	1.8	-	1.8	-	1.8	V
PCP <sub>OUT</sub> , PCn OUT	V <sub>OH</sub>	V <sub>IL</sub> or V <sub>IH</sub>	-0.02	2	1.9	-	-	1.9	-	1.9	-	V
High-Level Output		"- "'		4.5	4.4	-	-	4.4	-	4.4	-	V
Voltage CMOS Loads				6	5.9	-	-	5.9	-	5.9	-	V
PCP <sub>OUT</sub> , PCn OUT	Voh	V <sub>IL</sub> or V <sub>IH</sub>	-4	4.5	3.98	-	-	3.84	-	3.7	-	V
High-Level Output Voltage TTL Loads			-5.2	6	5.48	-	-	5.34	-	5.2	-	V
PCP <sub>OUT</sub> , PCn OUT	V <sub>OL</sub>	V <sub>IL</sub> or V <sub>IH</sub>	0.02	2	-	-	0.1	-	0.1	-	0.1	V
Low-Level Output				4.5	-	-	0.1	-	0.1	-	0.1	V
Voltage CMOS Loads				6	-	-	0.1	-	0.1	-	0.1	V
PCP <sub>OUT</sub> , PCn OUT	V <sub>OL</sub>	V <sub>IL</sub> or V <sub>IH</sub>	4	4.5	-	-	0.26	-	0.33	-	0.4	V
Low-Level Output Voltage TTL Loads			5.2	6	-	-	0.26	-	0.33	-	0.4	V
SIG <sub>IN</sub> , COMP <sub>IN</sub> Input	l <sub>l</sub>	V <sub>CC</sub> or	-	2	-	-	±3	-	±4	-	±5	μΑ
Leakage Current		GND		3	-	-	±7	-	±9	-	±11	μΑ
				4.5	-	-	±18	-	±23	-	±29	μΑ
				6	-	-	±30	-	±38	-	±45	μΑ
PC2 <sub>OUT</sub> Three-State Off-State Current	l <sub>OZ</sub>	V <sub>IL</sub> or V <sub>IH</sub>	-	6	-	-	±0.5	-	±5	-	±10	μА
SIG <sub>IN</sub> , COMP <sub>IN</sub> Input	R <sub>I</sub>	V <sub>I</sub> at Se		3	-	800	-	-	-	-	-	kΩ
Resistance		Operatio $\Delta V_I = 0$		4.5	-	250	-	-	-	-	-	kΩ
		See Fig		6	-	150	-	-	-	-	-	kΩ
DEMODULATOR SEC	TION	•					•					
Resistor Range	R <sub>S</sub>	at R <sub>S</sub> >		3	50	-	300	-	-	-	-	kΩ
		Leakage Can Infl		4.5	50	-	300	-	-	-	-	kΩ
		V <sub>DEM</sub>		6	50	-	300	-	-	-	-	kΩ

# DC Electrical Specifications (Continued)

		CONDITE STATES		V <sub>CC</sub>		25°C		-40°C	го 85°C	-55°C T	O 125°C	
PARAMETER	SYMBOL	V <sub>I</sub> (V)	I <sub>O</sub> (mA)	(V)	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNITS
Offset Voltage VCO <sub>IN</sub>	V <sub>OFF</sub>	$V_I = V_{VC}$	CO IN =	3	-	±30	-	-	-	-	-	mV
to V <sub>DEM</sub>		V <sub>CC</sub>		4.5	-	±20	-	-	-	-	-	mV
		Values Tal R <sub>S</sub> Ra See Fig	ange	6	-	±10	-	-	-	-	-	mV
Dynamic Output	R <sub>D</sub>	VDEMO	DUT =	3	-	25	-	-	-	-	-	Ω
Resistance at		$\frac{V_{CC}}{2}$		4.5	-	25	-	-	-	-	-	Ω
DEM <sub>OUT</sub>		_		6	-	25	-	-	-	-	-	Ω
Quiescent Device Current	Icc	Pins 3, 5 at V <sub>CC</sub> F GND, I <sub>1</sub> a and 14 exclu	Pin 9 at at Pins 3 to be	6	-	-	8	-	80	-	160	μА
HCT TYPES	•		<u> </u>						!			
VCO SECTION												
INH High Level Input Voltage	V <sub>IH</sub>	-	-	4.5 to 5.5	2	-	-	2	-	2	-	V
INH Low Level Input Voltage	V <sub>IL</sub>	-	-	4.5 to 5.5	-	-	0.8	-	0.8	-	0.8	V
VCO <sub>OUT</sub> High Level Output Voltage CMOS Loads	V <sub>ОН</sub>	V <sub>IH</sub> or V <sub>IL</sub>	-0.02	4.5	4.4	-	-	4.4	-	4.4	-	V
VCO <sub>OUT</sub> High Level Output Voltage TTL Loads			-4	4.5	3.98	-	-	3.84	-	3.7	-	V
VCO <sub>OUT</sub> Low Level Output Voltage CMOS Loads	V <sub>OL</sub>	V <sub>IH</sub> or V <sub>IL</sub>	0.02	4.5	-	-	0.1	-	0.1	-	0.1	V
VCO <sub>OUT</sub> Low Level Output Voltage TTL Loads			4	4.5	-	-	0.26	-	0.33	-	0.4	V
C1A, C1B Low Level Output Voltage (Test Purposes Only)	V <sub>OL</sub>	V <sub>IH</sub> or V <sub>IL</sub>	4	4.5	-	-	0.40	-	0.47	-	0.54	V
INH VCO <sub>IN</sub> Input Leakage Current	lı	Any Vo Between V GN	$V_{CC}$ and	5.5	-		±0.1	-	±1	-	±1	μА
R1 Range (Note 2)	-	-	-	4.5	3	-	300	-	-	-	-	kΩ
R2 Range (Note 2)	-	-	-	4.5	3	-	300	-	-	-	-	kΩ
C1 Capacitance Range	-	-	-	4.5	0	-	No Limit	-	-	-	-	pF
VCO <sub>IN</sub> Operating Voltage Range	-	Over the specified f Linearity So 10, and (Note	or R1 for ee Figure 34 - 37	4.5	1.1	-	3.2	-	-	-	-	V
PHASE COMPARATO	OR SECTIO	N										
SIG <sub>IN</sub> , COMP <sub>IN</sub> DC Coupled High-Level Input Voltage	V <sub>IH</sub>	-	-	4.5 to 5.5	2	-	-	2	-	2	-	V

# DC Electrical Specifications (Continued)

		TE:		V <sub>CC</sub>		25°C		-40°C 1	го 85°C	-55°C T	O 125°C	
PARAMETER	SYMBOL	V <sub>I</sub> (V)	I <sub>O</sub> (mA)	(V)	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNITS
SIG <sub>IN</sub> , COMP <sub>IN</sub> DC Coupled Low-Level Input Voltage	V <sub>IL</sub>	-	-	4.5 to 5.5	-	-	0.8	-	0.8	-	0.8	V
PCP <sub>OUT</sub> , PCn OUT High-Level Output Voltage CMOS Loads	V <sub>OH</sub>	V <sub>IL</sub> or V <sub>IH</sub>	-	4.5	4.4	-	-	4.4	-	4.4	-	V
PCP <sub>OUT</sub> , PCn OUT High-Level Output Voltage TTL Loads	V <sub>OH</sub>	V <sub>IL</sub> or V <sub>IH</sub>	-	4.5	3.98	-	-	3.84	-	3.7	-	V
PCP <sub>OUT</sub> , PCn OUT Low-Level Output Voltage CMOS Loads	V <sub>OL</sub>	V <sub>IL</sub> or V <sub>IH</sub>	-	4.5	-	-	0.1	-	0.1	-	0.1	V
PCP <sub>OUT</sub> , PCn OUT Low-Level Output Voltage TTL Loads	V <sub>OL</sub>	V <sub>IL</sub> or V <sub>IH</sub>	-	4.5	-	-	0.26	-	0.33	-	0.4	V
SIG <sub>IN</sub> , COMP <sub>IN</sub> Input Leakage Current	Ι <sub>Ι</sub>	Any Voltage Between V <sub>CC</sub> and GND	-	5.5	-	-	±30		±38		±45	μА
PC2 <sub>OUT</sub> Three-State Off-State Current	l <sub>OZ</sub>	V <sub>IL</sub> or V <sub>IH</sub>	-	5.5	-	-	±0.5	±5	-	-	±10	μА
SIG <sub>IN</sub> , COMP <sub>IN</sub> Input Resistance	R <sub>I</sub>	$V_{l}$ at Se Operatio $\Delta V_{l}$ = See Fig	n Point: 0.5V,	4.5	-	250	-	-	-	-	-	kΩ
DEMODULATOR SEC	CTION						_					_
Resistor Range	R <sub>S</sub>	at R <sub>S</sub> > Leakage Can Inf V <sub>DEM</sub>	Current luence	4.5	5	-	300	-	-	-	-	kΩ
Offset Voltage VCO <sub>IN</sub> to V <sub>DEM</sub>	Voff	$V_{I} = V_{VG}$ $\frac{V_{CC}}{2}$ $Values ta$ $R_{S} R_{i}$ $See Fig$	ken over ange	4.5	-	±20	-	-	-	-	-	mV
Dynamic Output Resistance at DEM <sub>OUT</sub>	R <sub>D</sub>	$\frac{V_{\text{DEM}}}{V_{\text{CC}}}$	TUC	4.5	-	25	-	-	-	-	-	Ω
Quiescent Device Current	Icc	V <sub>CC</sub> or GND	-	5.5	-	-	8	-	80	-	160	μА
Additional Quiescent Device Current Per Input Pin: 1 Unit Load	ΔI <sub>CC</sub> (Note 4)	V <sub>CC</sub> -2.1 Excluding Pin 5	-	4.5 to 5.5	-	100	360	-	450	-	490	μА

#### NOTES:

- 2. The value for R1 and R2 in parallel should exceed 2.7k $\!\Omega.$
- 3. The maximum operating voltage can be as high as  $V_{CC}$  -0.9V, however, this may result in an increased offset voltage.
- 4. For dual-supply systems theoretical worst case ( $V_I$  = 2.4V,  $V_{CC}$  = 5.5V) specification is 1.8mA.

# **HCT Input Loading Table**

INPUT	UNIT LOADS
INH	1

NOTE: Unit load is  $\Delta I_{CC}$  limit specific in DC Electrical Specifications Table, e.g., 360 $\mu$ A max. at 25 $^{o}$ C.

# **Switching Specifications** $C_L = 50pF$ , Input $t_r$ , $t_f = 6ns$

		TEST			25°C		-40°( 85	С ТО °С		C TO 5°C	
PARAMETER	SYMBOL	CONDITIONS	V <sub>CC</sub> (V)	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNITS
HC TYPES					•	•				•	
PHASE COMPARATOR SECTI	ON										
Propagation Delay	t <sub>PLH</sub> , t <sub>PHL</sub>										
$SIG_{IN}$ , $COMP_{IN}$ to $PCI_{OUT}$			2	-	-	200	-	250	-	300	ns
			4.5	-	-	40	-	50	-	60	ns
			6	-	-	34	-	43	-	51	ns
$SIG_{IN}$ , $COMP_{IN}$ to $PCP_{OUT}$			2	-	-	300	-	375	-	450	ns
			4.5	-	-	60	-	75	-	90	ns
			6	-	-	51	-	64	-	77	ns
SIG <sub>IN</sub> , COMP <sub>IN</sub> to PC3 <sub>OUT</sub>			2	-	-	245	-	305	-	307	ns
			4.5	-	-	49	-	61	-	74	ns
			6	-	-	42	-	52	-	63	ns
Output Transition Time	t <sub>THL</sub> , t <sub>TLH</sub>		2	-	-	75	-	95	-	110	ns
			4.5	-	-	15	-	19	-	22	ns
			6	-	-	13	-	16	-	19	ns
Output Enable Time, SIG <sub>IN</sub> ,	t <sub>PZH</sub> , t <sub>PZL</sub>		2	-	-	265	-	330	-	400	ns
COMP <sub>IN</sub> to PC2 <sub>OUT</sub>			4.5	ı	-	53	ı	66	1	80	ns
			6	ı	-	45	ı	56	1	68	ns
Output Disable Time, SIG <sub>IN</sub> ,	t <sub>PHZ</sub> , t <sub>PLZ</sub>		2	-	-	315	-	395	-	475	ns
COMP <sub>IN</sub> to PC2 <sub>OUT</sub>			4.5	-	-	63	-	79	-	95	ns
			6	-	-	54	-	67	-	81	ns
AC Coupled Input Sensitivity		V <sub>I(P-P)</sub>	3	-	11	-	-	-	-	-	mV
$(P-P)$ at $SIG_{IN}$ or $COMP_{IN}$			4.5	-	15	-	-	-	-	-	mV
			6	-	33	-	-	-	-	-	mV
VCO SECTION											
Frequency Stability with	Δf	$R_1 = 100k\Omega$ ,	3	-	0.11	-	-	-	-	-	%/ºC
Temperature Change	$\overline{\Delta}\overline{T}$	R <sub>2</sub> = ∞	4.5	-	0.11	-	-	-	-	-	%/ºC
			6	-	0.11	-	-	-	-	-	%/ºC
Maximum Frequency	f <sub>MAX</sub>	C <sub>1</sub> = 50pF	3	-	24	-	-	-	-	-	MHz
		$R_1 = 3.5k\Omega$ $R_2 = \infty$	4.5	-	24	-	-	-	-	-	MHz
		2	6	-	24	-	-	-	-	-	MHz
		C <sub>1</sub> = 0pF	3	-	38	-	-	-	-	-	MHz
		$R_1 = 9.1k\Omega$ $R_2 = \infty$	4.5	-	38	-	-	-	-	-	MHz
		· · · <b>Z</b>	6	-	38	-	-	-	-	-	MHz

# Switching Specifications $C_L = 50 pF$ , Input $t_r$ , $t_f = 6 ns$ (Continued)

		TEST			25°C		-40°( 85			C TO 5°C	
PARAMETER	SYMBOL	CONDITIONS	V <sub>CC</sub> (V)	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNITS
Center Frequency		$C_1 = 40pF$	3	7	10	-	-	-	-	-	MHz
		$R_1 = 3k\Omega$ $R_2 = \infty$	4.5	12	17	-	-	-	-	-	MHz
		VCO <sub>IN</sub> = VCC/2	6	14	21	-	-	-	-	-	MHz
Frequency Linearity	$\Delta f_{VCO}$	$R_1 = 100k\Omega$	3	-	0.4	-	-	-	-	-	%
		$R_2 = \infty$ $C_1 = 100pF$	4.5	-	0.4	-	-	-	-	-	%
			6	-	0.4	-	-	-	-	-	%
Offset Frequency		$R_2 = 220k\Omega$	3	-	400	-	-	-	-	-	kHz
		C <sub>1</sub> = 1nF	4.5	-	400	-	-	-	-	-	kHz
			6	-	400	-	-	-	-	-	kHz
DEMODULATOR SECTION	•										
V <sub>OUT</sub> V <sub>S</sub> f <sub>IN</sub>		$R_1 = 100k\Omega$	3	-	-	-	-	-	-	-	mV/kHz
		$R_2 = \infty$ $C_1 = 100pF$	4.5	-	330	-	-	-	-	-	mV/kH
		$R_S = 10k\Omega$ $R_3 = 100k\Omega$ $C_2 = 100pF$	6	ı	-	-	-	-	-	-	mV/kHz
HCT TYPES		-Z			<u> </u>						
PHASE COMPARATOR SECT	ION										
Propagation Delay	t <sub>PHL</sub> , t <sub>PLH</sub>				<u> </u>					1	
SIG <sub>IN</sub> , COMP <sub>IN</sub> to PCI <sub>OUT</sub>	PHL, PLH	$C_L = 50pF$	4.5	-	-	45	-	56	-	68	ns
SIG <sub>IN</sub> , COMP <sub>IN</sub> to PCP <sub>OUT</sub>	t <sub>PHL</sub> , t <sub>PLH</sub>	C <sub>L</sub> = 50pF	4.5	-	-	68	-	85	-	102	ns
SIG <sub>IN</sub> , COMP <sub>IN</sub> to PC3 <sub>OUT</sub>	t <sub>PHL</sub> , t <sub>PLH</sub>	C <sub>L</sub> = 50pF	4.5	-	-	58	-	73	-	87	ns
Output Transition Time	t <sub>TLH</sub> , t <sub>THL</sub>	C <sub>L</sub> = 50pF	4.5	-	-	15	-	19	-	22	ns
Output Enable Time, SIG <sub>IN</sub> , COMP <sub>IN</sub> to PC2 <sub>OUT</sub>	t <sub>PZH</sub> , t <sub>PZL</sub>	C <sub>L</sub> = 50pF	4.5	-	-	60	-	75	-	90	pF
Output Disable Time, $SIG_{IN}$ , $COMP_{IN}$ to $PCZ_{OUT}$	t <sub>PHZ</sub> , t <sub>PLZ</sub>	C <sub>L</sub> = 50pF	4.5	-	-	68	-	85	-	102	pF
AC Coupled Input Sensitivity (P-P) at SIGIN or COMPI		V <sub>I(P-P)</sub>	4.5	-	15	-	-	-	-	-	mV
VCO SECTION											
Frequency Stability with Temperature Change	$\frac{\Delta f}{\overline{\Delta T}}$	$R_1 = 100k\Omega$ , $R_2 = \infty$	4.5	-	0.11	-	-	-	-	-	%/ºC
Maximum Frequency	f <sub>MAX</sub>	$C_1 = 50pF$ $R_1 = 3.5k\Omega$ $R_2 = \infty$	4.5	-	24	-	-	-	-	-	MHz
		$C_1 = 0pF$ $R_1 = 9.1k\Omega$ $R_2 = \infty$	4.5	-	38	-	-	-	-	-	MHz
Center Frequency		$C_1 = 40pF$ $R_1 = 3k\Omega$ $R_2 = \infty$ $VCO_{IN} =$ $VCC/2$	4.5	12	17	-	-	-	-	-	MHz
Frequency Linearity	Δf <sub>VCO</sub>	$R_1 = 100k\Omega$ $R_2 = \infty$ $C_1 = 100pF$	4.5	-	0.4	-	-	-	-	-	%

#### Switching Specifications $C_L = 50pF$ , Input $t_r$ , $t_f = 6ns$ (Continued)

		TEST			25°C		-40°C TO 85°C		-55°C TO 125°C			
PARAMETER	SYMBOL	CONDITIONS	V <sub>CC</sub> (V)	MIN	TYP	MAX	MIN	MAX	MIN	MAX	UNITS	
Offset Frequency		$R_2 = 220k\Omega$ $C_1 = 1nF$	4.5	-	400	-	-	-	-	-	kHz	
DEMODULATOR SECTION												
Vout Vs fin		$R_1 = 100k\Omega$ $R_2 = \infty$ $C_1 = 100pF$ $R_S = 10k\Omega$ $R_3 = 100k\Omega$ $C_2 = 100pF$	4.5	-	330	-	-	-	-	-	mV/kHz	

#### Test Circuits and Waveforms

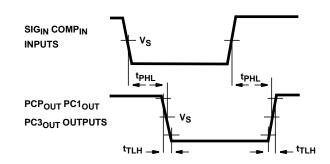


FIGURE 8. INPUT TO OUTPUT PROPAGATION DELAYS AND OUTPUT TRANSITION TIMES

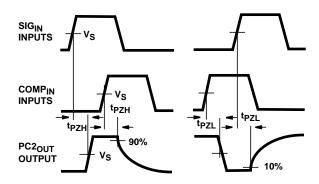


FIGURE 9. THREE STATE ENABLE AND DISABLE TIMES FOR  $\mathsf{PC2}_\mathsf{OUT}$ 

# **Typical Performance Curves**

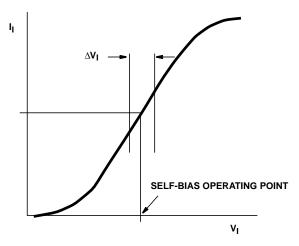


FIGURE 10. TYPICAL INPUT RESISTANCE CURVE AT  ${\rm SIG_{IN}},$   ${\rm COMP_{IN}}$ 

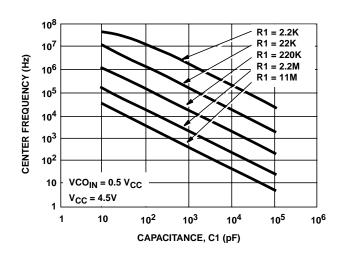


FIGURE 11. HC4046A TYPICAL CENTER FREQUENCY vs R1, C1 ( $V_{CC} = 4.5V$ )

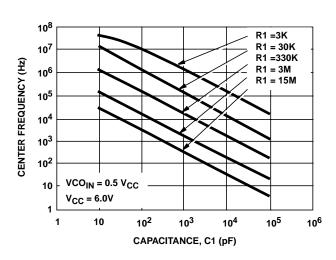


FIGURE 12. HC4046A TYPICAL CENTER FREQUENCY vs R1, C1 (V<sub>CC</sub> = 6V)

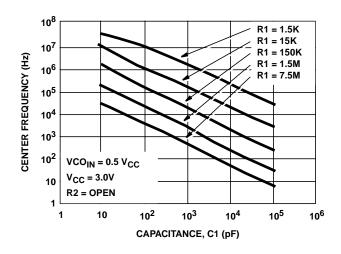


FIGURE 13. HC4046A TYPICAL CENTER FREQUENCY vs R1, C1 (V<sub>CC</sub> = 3V, R2 = OPEN)

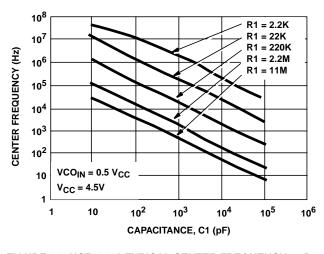


FIGURE 14. HCT4046A TYPICAL CENTER FREQUENCY vs R1, C1 (V<sub>CC</sub> = 4.5V)

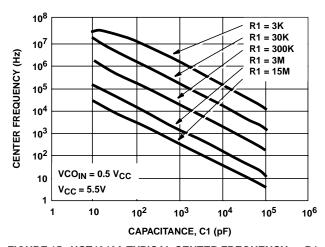


FIGURE 15. HCT4046A TYPICAL CENTER FREQUENCY vs R1, C1 ( $V_{CC} = 5.5V$ )

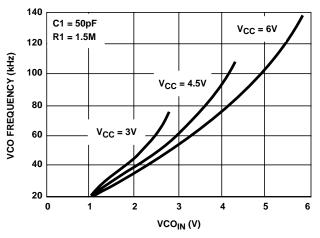


FIGURE 16. HC4046A TYPICAL VCO FREQUENCY vs VCO $_{\mbox{\scriptsize IN}}$  (R1 = 1.5M $_{\mbox{\scriptsize \Omega}}$ , C1 = 50pF)

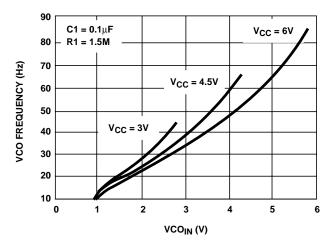


FIGURE 17. HC4046A TYPICAL VCO FREQUENCY vs VCO\_IN (R1 =  $1.5M\Omega$ , C1 =  $0.1\mu F$ )

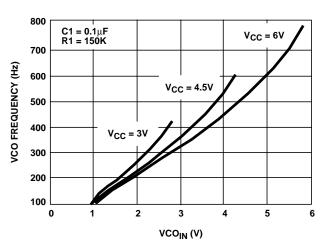


FIGURE 18. HC4046A TYPICAL VCO FREQUENCY vs VCO IN (R1 = 150k $\Omega$ , C1 = 0.1 $\mu$ F)

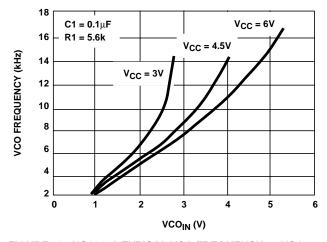


FIGURE 19. HC4046A TYPICAL VCO FREQUENCY vs VCO<sub>IN</sub>  $(R1 = 5.6k\Omega, C1 = 0.1\mu F)$ 

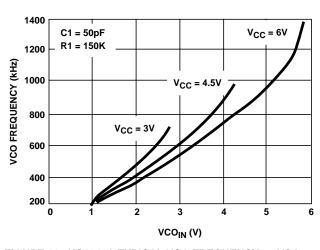


FIGURE 20. HC4046A TYPICAL VCO FREQUENCY vs VCO<sub>IN</sub> (R1 = 150k $\Omega$ , C1 = 50pF)

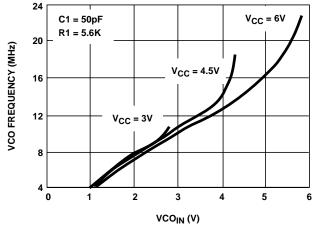


FIGURE 21. HC4046A TYPICAL VCO FREQUENCY vs VCO $_{IN}$  (R1 = 5.6k $\Omega$ , C1 = 50pF)

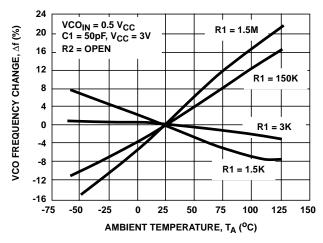


FIGURE 22. HC4046A TYPICAL CHANGE IN VCO FREQUENCY vs AMBIENT TEMPERATURE AS A FUNCTION OF R1 ( $V_{CC}$  = 3V)

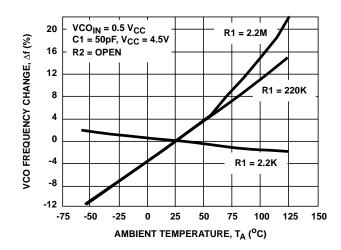


FIGURE 23. HC4046A TYPICAL CHANGE IN VCO FREQUENCY VS AMBIENT TEMPERATURE AS A FUNCTION OF R1 (V<sub>CC</sub> = 4.5V)

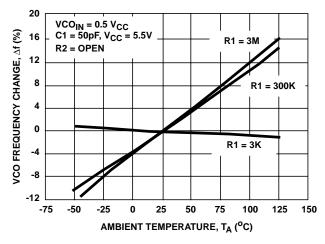


FIGURE 25. HCT4046A TYPICAL CHANGE IN VCO FREQUENCY vs AMBIENT TEMPERATURE AS A FUNCTION OF R1

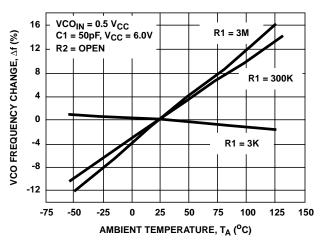


FIGURE 24. HC4046A TYPICAL CHANGE IN VCO FREQUENCY VS AMBIENT TEMPERATURE AS A FUNCTION OF R1 (V<sub>CC</sub> = 6V)

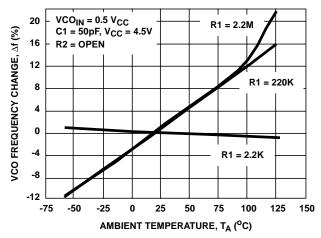


FIGURE 26. HC4046A TYPICAL CHANGE IN VCO FREQUENCY vs AMBIENT TEMPERATURE AS A FUNCTION OF R1 (V<sub>CC</sub> = 4.5V)

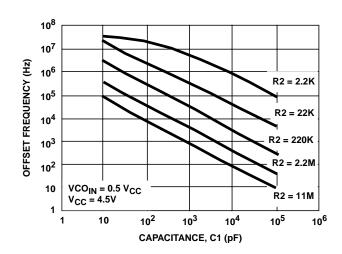


FIGURE 27. HC4046A OFFSET FREQUENCY vs R2, C1 ( $V_{CC} = 4.5V$ )

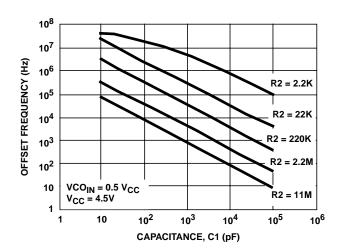


FIGURE 29. HCT4046A OFFSET FREQUENCY vs R2, C1  $(V_{CC} = 4.5V)$ 

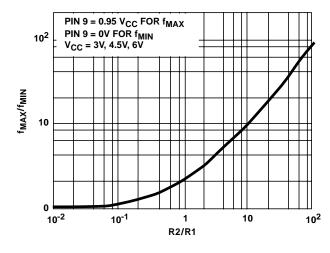


FIGURE 31. HC4046A  $f_{MIN}/f_{MAX}$  vs R2/R1 ( $V_{CC} = 3V, 4.5V, 6V$ )

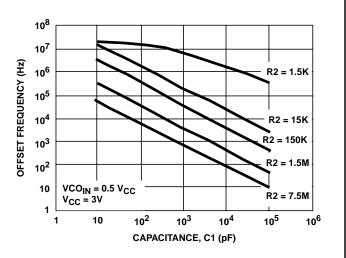


FIGURE 28. HC4046A OFFSET FREQUENCY vs R2, C1  $(V_{CC} = 3V)$ 

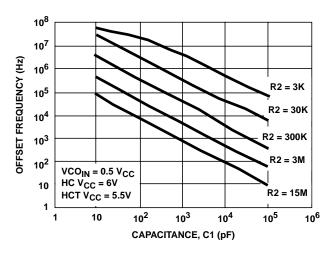


FIGURE 30. HC4046A AND HCT4046A OFFSET FREQUENCY vs R2, C1 ( $V_{CC}$  = 6V,  $V_{CC}$  = 5.5V)

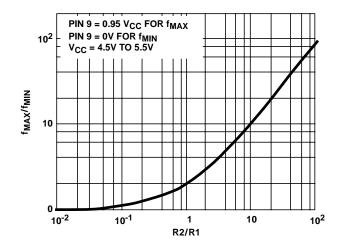


FIGURE 32. HCT4046A  $f_{MAX}/f_{MIN}$  vs R2/R1 ( $V_{CC} = 4.5V$  TO 5.5V)

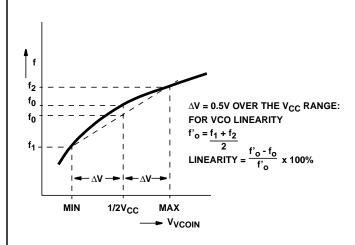


FIGURE 33. DEFINITION OF VCO FREQUENCY LINEARITY

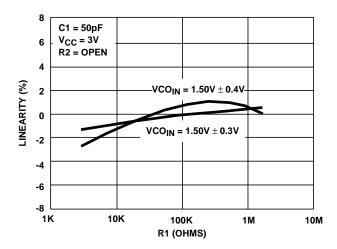


FIGURE 35. HC4046A VCO LINEARITY vs R1 (V<sub>CC</sub> = 3V)

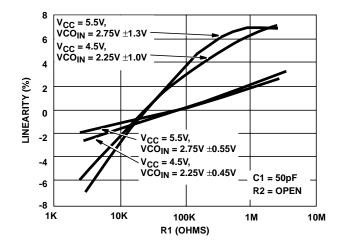


FIGURE 37. HCT4046A VCO LINEARITY vs R1 ( $V_{CC}$  = 4.5V,  $V_{CC}$  = 5.5V)

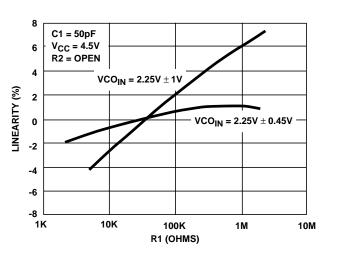


FIGURE 34. HC4046A VCO LINEARITY vs R1 (V<sub>CC</sub> = 4.5V)

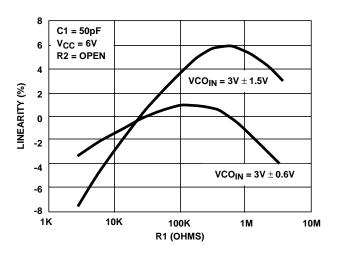


FIGURE 36. HC4046A VCO LINEARITY vs R1 (V<sub>CC</sub> = 6V)

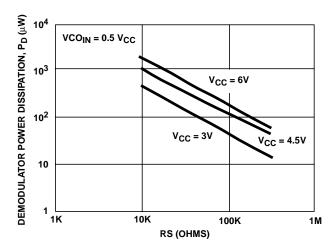
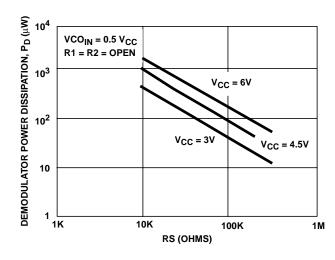


FIGURE 38. HC4046A DEMODULATOR POWER DISSIPATION vs RS (TYP) ( $V_{CC} = 3V, 4.5V, 6V$ )



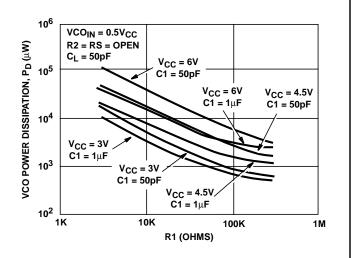
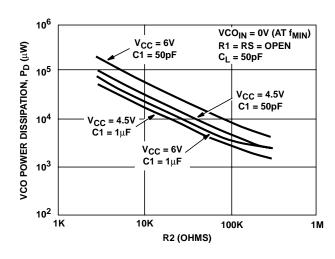


FIGURE 39. HCT4046A DEMODULATOR POWER DISSIPATION vs RS (TYP) ( $V_{CC}$  = 3V, 4.5V, 6V)





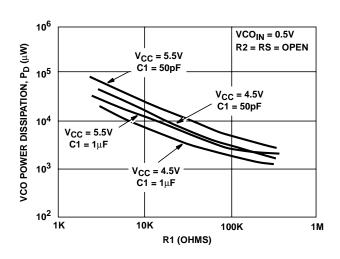


FIGURE 41. HCT4046A VCO POWER DISSIPATION vs R2 (C1 = 50pF,  $1\mu$ F)

FIGURE 42. HCT4046A VCO POWER DISSIPATION vs R1 (C1 = 50pF,  $1\mu$ F)

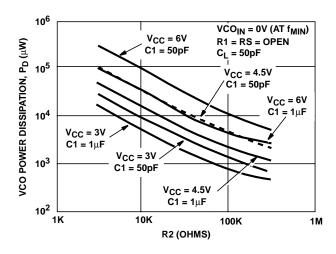


FIGURE 43. HC4046A VCO POWER DISSIPATION vs R2 (C1 = 50pF,  $1\mu$ F)

#### HC/HCT4046A CPD

CHIP SECTION	нс	нст	UNIT
Comparator 1	48	50	pF
Comparators 2 and 3	39	48	pF
vco	61	53	pF

Application Information

This information is a guide for the approximation of values of external components to be used with the 'HC4046A and 'HCT4046A in a phase-lock-loop system.

References should be made to Figures 11 through 15 and Figures 27 through 32 as indicated in the table.

Values of the selected components should be within the following ranges:

R1	Between $3k\Omega$ and $300k\Omega$
R2	Between $3\text{k}\Omega$ and $300\text{k}\Omega$
R1 + R2	Parallel Value > $2.7k\Omega$
C1	Greater Than 40pF

SUBJECT	PHASE COMPARATOR	DESIGN CONSIDERATIONS		
VCO Frequency Without Extra Offset	PC1, PC2 or PC3	VCO Frequency Characteristic With R2 = $\infty$ and R1 within the range $3k\Omega < R1 < 300k\Omega$ , the characteristics of the VCO operation will be as shown in Figures 11 - 15. (Due to R1, C1 time constant a small offset remains when R2 = $\infty$ .)		
		f <sub>MAX</sub>		
		fvco		
		f <sub>o</sub> - 2f <sub>L</sub>		
		f <sub>MIN</sub> MIN 1/2 Vocani MAX		
		MIN 1/2 V <sub>CC</sub> V <sub>VCOIN</sub> MAX  FIGURE 44. FREQUENCY CHARACTERISTIC OF VCO OPERATING WITHOUT  OFFSET: f <sub>o</sub> = CENTER FREQUENCY: 2f <sub>L</sub> = FREQUENCY LOCK RANGE		
	PC1	Selection of R1 and C1 Given f <sub>0</sub> , determine the values of R1 and C1 using Figures 11 - 15		
	PC2 or PC3	Given $f_{MAX}$ calculate $f_{O}$ as $f_{MAX}/2$ and determine the values of R1 and C1 using Figures 11 - 15. To obtain $2f_{L}$ : $2f_{L} \approx 1.2 \ (V_{CC} - 1.8V)/(R1C1)$ where valid range of $VCO_{IN}$ is $1.1V < VCO_{IN} < V_{CC} - 0.9V$		
VCO Frequency with Extra Offset	PC1, PC2 or PC3	VCO Frequency Characteristic With R1 and R2 within the ranges $3k\Omega$ < R1 < $300k\Omega$ , $3k\Omega$ , < R2 < $300k\Omega$ , the characte of the VCO operation will be as shown in Figures 27 - 32.		
		f <sub>MAX</sub> f <sub>VCO</sub>		
		f <sub>o</sub> 2f <sub>L</sub>		
		fmin		
		MIN 1/2 V <sub>CC</sub> V <sub>VCOIN</sub> MAX  FIGURE 45. FREQUENCY CHARACTERISTIC OF VCO OPERATING WITH OFFSET:		
		f <sub>o</sub> = CENTER FREQUENCY: 2f <sub>L</sub> = FREQUENCY LOCK RANGE		
	PC1, PC2 or PC3	Selection of R1, R2 and C1 Given $f_0$ and $f_L$ , offset frequency, $f_{MIN}$ , may be calculated from $f_{MIN} \approx f_0$ - 1.6 $f_L$ . Obtain the values of C1 and R2 by using Figures 27 - 30. Calculate the values of R1 from Figures 31 - 32.		

SUBJECT	PHASE COMPARATOR	DESIGN CONSIDERATIONS		
PLL Conditions with	PC1	VCO adjusts to $f_0$ with $\phi_{DEMOUT} = 90^{\circ}$ and $V_{VCOIN} = 1/2 V_{CC}$ (see Figure 2)		
No Signal at the	PC2	VCO adjusts to $f_{MIN}$ with $\phi_{DEMOUT} = -360^{\circ}$ and $V_{VCOIN} = 0V$ (see Figure 4)		
SIG <sub>IN</sub> Input	PC3	VCO adjusts to f <sub>MAX</sub> with $\phi_{DEMOUT} = 360^{\circ}$ and $V_{VCOIN} = V_{CC}$ (see Figure 6)		
PLL Frequency Capture Range	PC1, PC2 or PC3	Loop Filter Component Selection		
		INPUT C2 OUTPUT  (A) $\tau = R3 \times C2$ (B) AMPLITUDE CHARACTERISTIC  (C) POLE-ZERO DIAGRAM  A small capture range $(2f_c)$ is obtained if $\tau > 2f_c \approx 1/\pi \ (2\pi f_1/\tau.)^{1/2}$		
PLI Locks on	PC1 or PC3	FIGURE 46. SIMPLE LOOP FILTER FOR PLL WITHOUT OFFSET $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		
PLL Locks on Harmonics at Center Frequency				
	PC2	No		
Noise Rejection at Signal Input	PC1	High		
	PC2 or PC3	Low		
AC Ripple Content	PC1	$f_r = 2f_i$ , large ripple content at $\phi_{DEMOUT} = 90^\circ$		
when PLL is Locked	PC2	$f_r = f_i$ , small ripple content at $\phi_{DEMOUT} = 0^0$		
	PC3	$f_r = fSIG_{IN}$ , large ripple content at $\phi_{DEMOUT} = 180^{\circ}$		

### 14 LEADS SHOWN



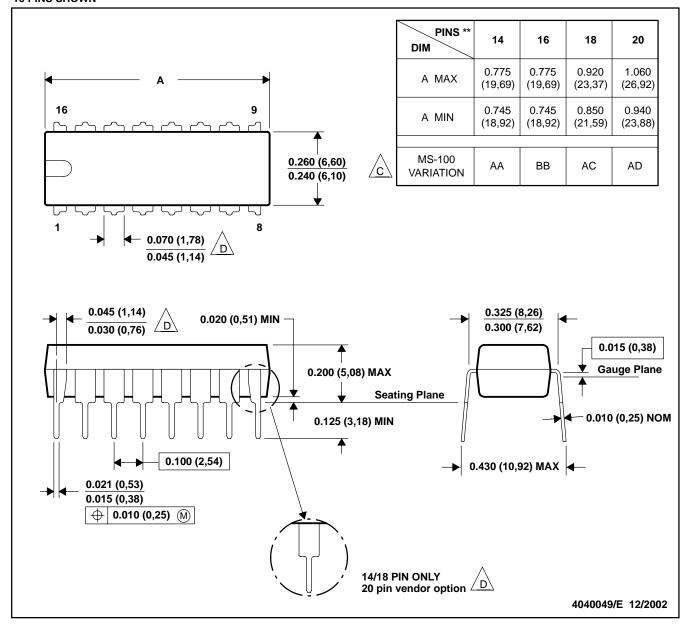
NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. This package is hermetically sealed with a ceramic lid using glass frit.
- D. Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.
- E. Falls within MIL STD 1835 GDIP1-T14, GDIP1-T16, GDIP1-T18 and GDIP1-T20.

#### N (R-PDIP-T\*\*)

#### **16 PINS SHOWN**

#### PLASTIC DUAL-IN-LINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

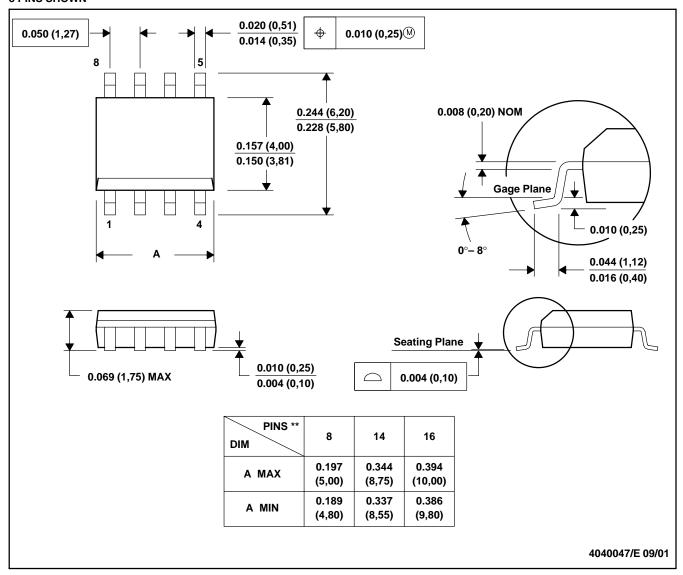
Falls within JEDEC MS-001, except 18 and 20 pin minimum body Irngth (Dim A).

The 20 pin end lead shoulder width is a vendor option, either half or full width.

#### D (R-PDSO-G\*\*)

#### PLASTIC SMALL-OUTLINE PACKAGE

#### **8 PINS SHOWN**



NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-012

#### **MECHANICAL DATA**

# NS (R-PDSO-G\*\*)

# 14-PINS SHOWN

#### PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion, not to exceed 0,15.



#### PW (R-PDSO-G\*\*)

#### 14 PINS SHOWN

#### PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.

D. Falls within JEDEC MO-153

#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Amplifiers	amplifier.ti.com	Audio	www.ti.com/audio
Data Converters	dataconverter.ti.com	Automotive	www.ti.com/automotive
DSP	dsp.ti.com	Broadband	www.ti.com/broadband
Interface	interface.ti.com	Digital Control	www.ti.com/digitalcontrol
Logic	logic.ti.com	Military	www.ti.com/military
Power Mgmt	power.ti.com	Optical Networking	www.ti.com/opticalnetwork
Microcontrollers	microcontroller.ti.com	Security	www.ti.com/security
		Telephony	www.ti.com/telephony
		Video & Imaging	www.ti.com/video
		Wireless	www.ti.com/wireless

Mailing Address: Texas Instruments

Post Office Box 655303 Dallas, Texas 75265

Copyright © 2003, Texas Instruments Incorporated